## The construction of perfect autocorrelation codes

John J. Benedetto Norbert Wiener Center Department of Mathematics University of Maryland, College Park

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www.norbertwiener.umd.edu

A significant underlying component for the effective design of phasecoded waveforms is the construction of finite unimodular codes whose autocorrelations are zero everywhere except at the dc-component. We refer to such codes as CAZACs, Constant Amplitude Zero AutoCorrelation codes.

We begin by describing some known results in the long history of this subject. Then we construct new CAZACs and show that there is an infinitude of distinct CAZACs. This is important in the realm of waveform diversity, especially as regards a fine local analysis of the ambiguity function and the solutions of both the narrow band and wide band radar ambiguity problems.

We also present the vector-valued theory as well as constructions of infinite CAZAC codes.

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Enrico Au-Yeung, John J. Benedetto,

Abdelkrim Bourouihiya, Wojciech Czaja, Michael R. Dellomo,

Jeffrey J. Donatelli, Matthew Fickus, Andrew Kebo,

Ioannis Konstantinidis, Kasso Okoudjou, Onur Oktay,

Joseph F. Ryan, Christopher S. Shaw,

Jeffrey M. Sieracki, Jesse Sugar-Moore.









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## Narrow band ambiguity functions and CAZAC codes

# Narrow band ambiguity functions and CAZAC codes



## Discrete ambiguity functions

Let  $u: \{0, 1, \ldots, N-1\} \rightarrow \mathbb{C}$ .

- $u_p : \mathbb{Z}_N \to \mathbb{C}$  is the *N*-periodic extension of *u*.
- $u_a : \mathbb{Z} \to \mathbb{C}$  is an aperiodic extension of u:

$$u_a[m] = \left\{ egin{array}{cc} u[m], & m=0,1,\ldots,N-1 \ 0, & ext{otherwise}. \end{array} 
ight.$$

The discrete periodic ambiguity function A<sub>p</sub>(u) : Z<sub>N</sub> × Z<sub>N</sub> → C of u is

$$A_{\rho}(u)(m,n)=\frac{1}{N}\sum_{k=0}^{N-1}u_{\rho}[m+k]\overline{u_{\rho}[k]}e^{2\pi i kn/N}.$$

The discrete aperiodic ambiguity function A<sub>a</sub>(u) : ℤ × ℤ → ℂ of u is

$$A_{a}(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} u_{a}[m+k] \overline{u_{a}[k]} e^{2\pi i k n/N}.$$

## The ambiguity function

The complex envelope w of the phase coded waveform Re(w) associated to a unimodular N-periodic sequence u : Z<sub>N</sub> → C is

$$w(t) = \frac{1}{\sqrt{\tau}} \sum_{k=0}^{N-1} u[k] \mathbb{1}\left(\frac{t-kt_b}{t_b}\right),$$

where  $\mathbb{1}$  is the characteristic function of the interval [0, 1),  $\tau$  is the pulse duration, and  $t_b = \tau/N$ .

- For spectral shaping problems, smooth replacements to 1 are analyzed.
- The (aperiodic) ambiguity function  $\mathcal{A}(w)$  of w is

$$\mathcal{A}(w)(t,\gamma) = \int w(s+t)\overline{w(s)}e^{2\pi i s \gamma} ds,$$

where  $t \in \mathbb{R}$  is time delay and  $\gamma \in \widehat{\mathbb{R}}(=\mathbb{R})$  is frequency shiftent Wener Center of the state of t

## **CAZAC** sequences

•  $u : \mathbb{Z}_N \to \mathbb{C}$  is Constant Amplitude Zero Autocorrelation (CAZAC):

 $\forall m \in \mathbb{Z}_N, |u[m]| = 1, (CA)$ 

and

 $\forall m \in \mathbb{Z}_N \setminus \{0\}, \quad A_p(u)(m,0) = 0.$  (ZAC)

- Empirically, the (ZAC) property of CAZAC sequences u leads to phase coded waveforms w with low *aperiodic autocorrelation*  $\mathcal{A}(w)(t, 0)$ .
- Are there only finitely many non-equivalent CAZAC sequences?
  - "Yes" for *N* prime and "No" for  $N = MK^2$ ,
  - Generally unknown for *N* square free and not prime.



- $u \text{ CAZAC} \Rightarrow u$  is broadband (full bandwidth).
- There are different constructions of different CAZAC codes resulting in different behavior vis à vis Doppler, additive noises, and approximation by bandlimited waveforms.
- $u \ CA \Leftrightarrow DFT$  of u is ZAC off dc. (DFT of u can have zeros)
- $u \text{ CAZAC} \Leftrightarrow \text{ DFT of } u \text{ is CAZAC}.$
- User friendly software: http://www.math.umd.edu/~jjb/cazac



K = 75 : u(x) = $(1, 1, 1, 1, 1, 1, e^{2\pi i \frac{1}{15}}, e^{2\pi i \frac{2}{15}}, e^{2\pi i \frac{1}{5}}, e^{2\pi i \frac{4}{15}}, e^{2\pi i \frac{3}{3}}, e^{2\pi i \frac{7}{15}}, e^{2\pi i \frac{3}{5}})$  $e^{2\pi i \frac{11}{15}}, e^{2\pi i \frac{13}{15}}, 1, e^{2\pi i \frac{5}{5}}, e^{2\pi i \frac{3}{5}}, e^{2\pi i \frac{3}{5}}, e^{2\pi i \frac{4}{5}}, 1, e^{2\pi i \frac{4}{15}}, e^{2\pi i$  $e^{2\pi i \frac{16}{15}}, e^{2\pi i \frac{3}{3}}, e^{2\pi i \frac{2}{3}}, e^{2\pi i}, e^{2\pi i \frac{4}{3}}, e^{2\pi i \frac{4}{3}}, e^{2\pi i \frac{5}{3}}, 1, e^{2\pi i \frac{2}{5}}, e^{2\pi i \frac{4}{5}}, e^{2\pi i \frac{4}{5}}$  $e^{2\pi i \frac{8}{5}}, 1, e^{2\pi i \frac{7}{15}}, e^{2\pi i \frac{14}{15}}, e^{2\pi i \frac{7}{5}}, e^{2\pi i \frac{28}{15}}, e^{2\pi i \frac{28}{15}}, e^{2\pi i \frac{13}{3}}, e^{2\pi i \frac{13}{15}}, e^{2\pi i \frac{7}{5}}, e^{2\pi i \frac{29}{15}}$  $e^{2\pi i \frac{37}{15}}, 1, e^{2\pi i \frac{3}{5}}, e^{2\pi i \frac{6}{5}}, e^{2\pi i \frac{9}{5}}, e^{2\pi i \frac{12}{5}}, 1, e^{2\pi i \frac{2}{3}}, e^{2\pi i \frac{4}{3}}, e^{2\pi i \cdot 2}, e^{2\pi i \frac{8}{3}}$  $e^{2\pi i \frac{1}{3}}, e^{2\pi i \frac{16}{15}}, e^{2\pi i \frac{9}{5}}, e^{2\pi i \frac{38}{15}}, e^{2\pi i \frac{49}{15}}, 1, e^{2\pi i \frac{4}{5}}, e^{2\pi i \frac{8}{5}}, e^{2\pi i \frac{12}{5}}, e^{2\pi i \frac{12}{5}}$  $1, e^{2\pi i \frac{13}{15}}, e^{2\pi i \frac{26}{15}}, e^{2\pi i \frac{33}{5}}, e^{2\pi i \frac{52}{15}}, e^{2\pi i \frac{13}{3}}, e^{2\pi i \frac{19}{15}}, e^{2\pi i \frac{19}{15}}, e^{2\pi i \frac{47}{15}}, e^{2\pi i \frac{27}{15}}, e^{$ 



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## Definition

A *quadratic phase* CAZAC  $u : \mathbb{Z}_N \to \mathbb{C}$  is given by

$$u[k] = e^{\pi i P(k)/N}, \quad k = 0, 1, \dots, N-1,$$

where P(k) is a quadratic polynomial.

Examples:

- Chu sequences: P(k) = k(k-1), N odd,
- P4 sequences: P(k) = k(k N),
- Wiener CAZAC sequences:  $P(k) = k^2$ , N odd.



## Wiener CAZAC codes



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#### Wiener CAZAC sequences

- Elementary number theoretic techniques, dealing with primitive roots of unity, are used to analyze Wiener CAZAC sequences.
- Peaks in the discrete ambiguity function  $A_p(u)$  of a Wiener CAZAC *u* are not stable under small perturbations in its domain, see [BD2007].



Different CAZACs exhibit different behavior in their ambiguity plots, according to their construction method. Thus, the ambiguity function reveals localization properties of different constructions.

#### Theorem

Given *K* odd, 
$$\zeta = e^{\frac{2\pi i}{K}}$$
, and  $u[k] = \zeta^{k^2}$ ,  $k \in \mathbb{Z}_K$ 

• 
$$1 \le k \le K - 2$$
 odd implies

$$m{A}[m,k]=m{e}^{\pi i (K-k)^2/K}$$
 for  $m=rac{1}{2}(K-k),$  and 0 elsewhere

•  $2 \le k \le K - 1$  even implies

$$A[m,k] = e^{\pi i (2K-k)^2/K}$$
 for  $m = \frac{1}{2}(2K-k)$ , and 0 elsewhere

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#### Theorem 1

Given  $N \ge 1$ . Let  $M = \begin{cases} N, & \text{N odd,} \\ 2N, & \text{N even,} \end{cases}$ and let  $\omega$  be a primitive *M*th root of unity. Define the Wiener waveform  $u : \mathbb{Z}_N \to \mathbb{C}$  by  $u(k) = \omega^{k^2}$ ,  $0 \le k \le N - 1$ . Then *u* is a CAZAC waveform.



#### Theorem 2

Let  $j \in \mathbb{Z}$ . Define  $u_j : \mathbb{Z}_N \to \mathbb{C}$  by  $u_j(k) = e^{2\pi i j k^2 / M}$ , where M = 2N if N is even and M = N if N is odd. If N is even, then

$$egin{aligned} \mathcal{A}_{u_j}(m,n) = \left\{ egin{aligned} e^{2\pi i j m^2/(2N)}, & jm+n \equiv 0 \mod N, \ 0, & ext{otherwise.} \end{aligned} 
ight. \end{aligned}$$

If N is odd

$$egin{aligned} \mathcal{A}_{u_j}(m,n) = \left\{ egin{aligned} e^{2\pi i j m^2/N}, & 2jm+n \equiv 0 \mod N, \ 0, & ext{otherwise}. \end{aligned} 
ight. \end{aligned}$$



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Finite frames

#### Rationale and theorem

*Proof.* Let *N* be even, and set  $u_j(k) = e^{\pi i j k^2 / N}$ . We calculate

$$\begin{aligned} A_{u_j}(m,n) &= \frac{1}{N} \sum_{k=0}^{N-1} u_j(m+k) \overline{u_j(k)} e^{2\pi i k n/N} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} e^{(\pi i/N)(jm^2 + 2jkm + 2kn)} = e^{\pi i jm^2/N} \frac{1}{N} \sum_{k=0}^{N-1} e^{2\pi i k (jm+n)/N}. \end{aligned}$$

If  $jm + n \equiv 0 \mod N$ , then

$$\frac{1}{N}\sum_{k=0}^{N-1}e^{2\pi ik(jm+n)/N} = 1.$$

Otherwise, we have

$$\frac{1}{N}\sum_{k=0}^{N-1}e^{2\pi ik(jm+n)/N} = \frac{e^{(2\pi i(jm+n)/N)N} - 1}{e^{2\pi i(jm+n)/N} - 1} = 0.$$
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*Proof.(Continued)* Let *N* be odd, and set  $u(k) = e^{2\pi i k^2/N}$ . We calculate

$$\begin{aligned} A_{u_j}(m,n) &= \frac{1}{N} \sum_{k=0}^{N-1} u_j(m+k) \overline{u_j(k)} e^{2\pi i k n/N} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} e^{(2\pi i/N)(jm^2 + 2jkm + kn)} = e^{2\pi i jm^2/N} \frac{1}{N} \sum_{k=0}^{N-1} e^{2\pi i k (2jm+n)/N}. \end{aligned}$$

If  $2jm + n \equiv 0 \mod N$ , then

$$\frac{1}{N}\sum_{k=0}^{N-1}e^{2\pi ik(2jm+n)/N}=1.$$

Otherwise, we have

$$\frac{1}{N}\sum_{k=0}^{N-1}e^{2\pi ik(2jm+n)/N} = \frac{e^{2\pi i(2m+n)/N}N - 1}{e^{(2\pi i(2m+n)/N} - 1} = 0.$$
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#### Corollary

Let  $\{u(k)\}_{k=0}^{N-1}$  be a Wiener CAZAC waveform as given in Theorem 1. (In particular,  $\omega$  is a primitive *M*-th root of unity.) If N is even, then

$${\cal A}_u(m,n)=\left\{egin{array}{cc} \omega^{m^2}, & m\equiv -n \ mod \ N,\ 0, & {
m otherwise}. \end{array}
ight.$$

If N is odd, then

$$A_u(m,n) = \begin{cases} \omega^{m^2}, & m \equiv -n(N+1)/2 \mod N, \\ 0, & \text{otherwise.} \end{cases}$$



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#### Example

a. Let *N* be odd and let  $\omega = e^{2\pi i/N}$ . Then,  $u(k) = \omega^{k^2}$ ,  $0 \le k \le N - 1$ , is a CAZAC waveform. By the Corollary,  $|A_u(m, n)| = |\omega^{m^2}| = 1$  if  $2m + n = I_{m,n}N$  for some  $I_{m,n} \in \mathbb{Z}$  and  $|A_u(m, n)| = 0$  otherwise, i.e.,  $A_u(m, n) = 0$  on  $\mathbb{Z}_N \times \mathbb{Z}_N$  unless  $2m + n \equiv 0 \mod N$ . In the case  $2m + n = I_{m,n}N$  for some  $I_{m,n} \in \mathbb{Z}$ , we have the following phenomenon.



#### Example (Continued)

If  $0 \le m \le \frac{N-1}{2}$  and  $2m + n = I_{m,n}N$  for some  $I_{m,n} \in \mathbb{Z}$ , then *n* is odd; and if  $\frac{N+1}{2} \le m \le N-1$  and  $2m + n = I_{m,n}N$  for some  $I_{m,n} \in \mathbb{Z}$ , then *n* is even. Thus, the values (m, n) in the domain of the discrete periodic ambiguity function  $A_u$ , for which  $A_u(m, n) = 0$ , appear as two parallel discrete lines. The line whose domain is  $0 \le m \le \frac{N-1}{2}$  has odd function values *n*; and the line whose domain is  $\frac{N+1}{2} \le m \le N-1$  has even function values *n*.



#### Example

b. The behavior observed in (a) has extensions for primitive and non-primitive roots of unity.

Let  $u : \mathbb{Z}_N \to \mathbb{C}$  be a Wiener waveform. Thus,  $u(k) = \omega^{k^2}$ ,  $0 \le k \le N - 1$ , and  $\omega = e^{2\pi i j/M}$ , (j, M) = 1, where *M* is defined in terms of *N* in Theorem 1. By the Corollary, for each fixed  $n \in \mathbb{Z}_N$ , the function  $A_u(\bullet, n)$  of *m* vanishes everywhere except for a *unique* value  $m_n \in \mathbb{Z}_N$  for which  $|A_u(m_n, n)| = 1$ .



#### **Example (Continued)**

The hypotheses of Theorem 2 do not assume that  $e^{2\pi i j/M}$  is a primitive *M*th root of unity. In fact, in the case that  $e^{2\pi i j/M}$  is *not* primitive, then, for certain values of n,  $A_u(\bullet, n)$  will be identically 0 and, for certain values of n,  $|A_u(\bullet, n)| = 1$  will have several solutions. For example, if N = 100 and j = 2, then, for each odd n,  $A_u(\bullet, n) = 0$  as a function of m. If N = 100 and j = 3, then (100, 3) = 1 so that  $e^{2\pi i/3/100}$  is a primitive 100th root of unity; and, in this case, for each  $n \in \mathbb{Z}_N$  there is a *unique*  $m_n \in \mathbb{Z}_N$  such that  $|A_u(m_n, n)| = 1$  and  $A_u(m, n) = 0$  for each  $m \neq m_n$ .





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Sequences for coding theory, cryptography, phase-coded waveforms, and communications (synchronization, fast start-up equalization, frequency hopping) include the following in the periodic case:

- Gauss, Wiener (1927), Zadoff (1963), Schroeder (1969), Chu (1972), Zhang and Golomb (1993)
- Frank (1953), Zadoff and Abourezk (1961), Heimiller (1961)
- Milewski (1983)
- Bjørck (1985) and Golomb (1992),

and their generalizations, both periodic and aperiodic.

The general problem of using codes to generate signals leads to frames.


# Frames



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#### Definition

A collection  $(e_n)_{n \in \Lambda}$  in a Hilbert space  $\mathcal{H}$  is a *frame* for  $\mathcal{H}$  if there exist  $0 < A \leq B < \infty$  such that

$$\forall x \in \mathcal{H}, \ A \|x\|^2 \leq \sum_{n \in \Lambda} |\langle x, e_n \rangle|^2 \leq B \|x\|^2.$$

The constants A and B are the *frame bounds*. If A = B, the frame is an A-*tight* frame.



#### Definition

• Bessel (analysis) operator L:  $\mathcal{H} \to \ell^2(\Lambda)$ 

$$Lx = (\langle x, e_n \rangle)$$

- Synthesis operator L\*, the Hilbert space adjoint of L
- Frame operator  $S = L^*L : \mathcal{H} \to \mathcal{H}$ ,

$$Sx = \sum \langle x, e_n \rangle e_n.$$

By the definition of frames, *S* satisfies  $AI \leq S \leq BI$ .

• Grammian operator  $G = LL^* : \ell^2(\Lambda) \to \ell^2(\Lambda)$ .



 $AI \leq S \leq BI$  implies that S is invertible and that  $B^{-1}I \leq S^{-1} \leq A^{-1}I$ .

#### Definition

Let  $F = \{e_n\}$  be a frame, and let  $\tilde{e}_n = S^{-1}e_n$ .  $\tilde{F} = \{\tilde{e}_n\}$  is the *dual frame* of *F*.

• 
$$\sum \langle x, e_n \rangle \widetilde{e}_n = S^{-1} \sum \langle x, e_n \rangle e_n = S^{-1} S x = x.$$

• 
$$\sum \langle x, \tilde{e}_n \rangle e_n = \sum \langle S^{-1}x, e_n \rangle e_n = SS^{-1}x = x.$$

• The frame operator of  $\tilde{F}$  is  $S^{-1}$  since

$$\sum \langle x, \widetilde{e}_n \rangle \widetilde{e}_n = S^{-1} \sum \langle S^{-1}x, e_n \rangle e_n = S^{-1}SS^{-1}x = S^{-1}x.$$

•  $\sum |\langle x, \widetilde{e}_n \rangle|^2 = \langle S^{-1}x, x \rangle$ . Then,

$$B^{-1}\|x\|^2 \leq \sum |\langle x, \widetilde{e}_n \rangle|^2 \leq A^{-1}\|x\|^2.$$



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### Frames





#### Theorem

Let *H* be a Hilbert space.

$$\{e_n\}_{n\in\Lambda}\subseteq H$$
 is A-tight  $\Leftrightarrow S=AI$ ,

where I is the identity operator.

*Proof.* ( $\Rightarrow$ ) If  $S = L^*L = AI$ , then  $\forall x \in H$ 

$$\begin{aligned} A\|x\|^2 &= A\langle x, x \rangle = \langle Ax, x \rangle = \langle Sx, x \rangle \\ &= \langle L^*Lx, x \rangle = \langle Lx, Lx \rangle \\ &= \|Ly\|_{l^2(\Lambda)}^2 \\ &= \sum_{i \in \Lambda} |\langle x, e_i \rangle|^2. \end{aligned}$$

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*Proof.* ( $\Leftarrow$ ) If  $\{e_i\}_{i \in \Lambda}$  is A-tight, then  $\forall x \in H, A(x, x)$  is

$$A\|x\|^{2} = \sum_{i \in K} |\langle x, e_{i} \rangle|^{2} = \sum_{i \in K} \langle x, e_{i} \rangle \langle e_{i}, x \rangle = \left\langle \sum_{i \in K} \langle x, e_{i} \rangle e_{i}, x \right\rangle = \langle Sx, x \rangle.$$

Therefore,

$$\forall x \in H, \quad \langle (S - AI)x, x \rangle = 0.$$

In particular, S - AI is Hermitian and positive semi-definite, so

 $\forall x, y \in H, \quad |\langle (S - AI)x, y \rangle| \le \sqrt{\langle (S - AI)x, x \rangle \langle (S - AI)y, y \rangle} = 0.$ Thus, (S - AI) = 0, so, S = AI.



#### Theorem (Vitali, 1921)

Let *H* be a Hilbert space,  $\{e_n\} \subseteq H$ ,  $||e_n|| = 1$ .

 $\{e_n\}$  is 1-tight  $\Leftrightarrow$   $\{e_n\}$  is an ONB.

*Proof.* If  $\{e_n\}$  is 1-tight, then  $\forall y \in H$ 

$$\|\mathbf{y}\|^2 = \sum_n |\langle \mathbf{y}, \mathbf{e}_n \rangle|^2.$$

Since each  $||e_n|| = 1$ , we have

$$1 = ||e_n||^2 = \sum_k |\langle e_n, e_k \rangle|^2 = 1 + \sum_{k,k \neq n} |\langle e_n, e_k \rangle|^2$$
$$\Rightarrow \sum_{k \neq n} |\langle e_n, e_k \rangle|^2 = 0 \Rightarrow \forall n \neq k, \ \langle e_n, e_k \rangle = 0$$
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Frames  $F = \{e_n\}_{n=1}^N$  for *d*-dimensional Hilbert space *H*, e.g.,  $H = \mathbb{K}^d$ , where  $\mathbb{K} = \mathbb{C}$  or  $\mathbb{K} = \mathbb{R}$ .

- Any spanning set of vectors in  $\mathbb{K}^d$  is a *frame* for  $\mathbb{K}^d$ .
- If  $\{e_n\}_{n=1}^N$  is a finite unit norm tight frame (FUNTF) for  $\mathbb{K}^d$ , with frame constant *A*, then A = N/d.
- {*e<sub>n</sub>*}<sup>*d*</sup><sub>*n*=1</sub> is a *A*-tight frame for K<sup>*d*</sup>, then it is a √*A*-normed orthogonal set.



## **Properties and examples of FUNTFs**

- Frames give redundant signal representation to compensate for hardware errors, to ensure numerical stability, and to minimize the effects of noise.
- Thus, if certain types of noises are known to exist, then the FUNTFs are constructed using this information.
- Orthonormal bases, vertices of Platonic solids, kissing numbers (sphere packing and error correcting codes) are FUNTFs.
- The vector-valued CAZAC FUNTF problem: Characterize  $u : \mathbb{Z}_K \longrightarrow \mathbb{C}^d$  which are CAZAC FUNTFs.



# FUNTF

• A set  $F = \{e_j\}_{j \in J} \subseteq \mathbb{F}^d$  is a *frame* for  $\mathbb{F}^d$ ,  $\mathbb{F} = \mathbb{R}$  or  $\mathbb{C}$ , if

$$\exists \ \textit{A},\textit{B} > 0 \quad \text{such that} \quad \forall \ \textit{x} \in \mathbb{F}^d, \quad \textit{A} \|\textit{x}\|^2 \leq \sum_{j \in J} |\langle \textit{x},\textit{e}_j \rangle|^2 \leq \textit{B} \|\textit{x}\|^2.$$

- *F* tight if A = B. A finite unit-norm tight frame *F* is a FUNTF.
- N row vectors from any fixed N × d submatrix of the N × N DFT matrix, 1/√d (e<sup>2πimn/N</sup>), is a FUNTF for C<sup>d</sup>.
- If F is a FUNTF for  $\mathbb{F}^d$ , then

$$\forall x \in \mathbb{F}^d, \quad x = \frac{d}{N} \sum_{j=1}^N \langle x, e_j \rangle e_j.$$

 Frames: redundant representation, compensate for hardware errors, inexpensive, numerical stability, minimize effects of noise representation.

- Robust transmission of data over erasure channels such as the internet [Casazza, Goyal, Kelner, Kovačevic]
- Multiple antenna code design for wireless communications [Hochwald, Marzetta,T. Richardson, Sweldens, Urbanke]
- Multiple description coding [Goyal, Heath, Kovačevic, Strohmer, Vetterli]
- Quantum detection [Bølcskei, Eldar, Forney, Oppenheim, Kebo, B]
- Grassmannian "min-max" waveforms [Calderbank, Conway, Sloane, et al., Kolesar, B]







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# **DFT FUNTFs**

 N × d submatrices of the N × N DFT matrix are FUNTFs for C<sup>d</sup>. These play a major role in finite frame ΣΔ-quantization.

$$N = 8, d = 5 \qquad \frac{1}{\sqrt{5}} \begin{bmatrix} * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \\ * & * & \cdot & \cdot & * & * & * & \cdot \end{bmatrix}$$
$$x_m = \frac{1}{5} (e^{2\pi i \frac{m}{8}}, e^{2\pi i \frac{m^2}{8}}, e^{2\pi i \frac{m^5}{8}}, e^{2\pi i \frac{m^6}{8}}, e^{2\pi i \frac{m^7}{8}})$$
$$m = 1, \dots, 8.$$

Sigma-Delta Super Audio CDs - but not all authorities are fans.

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#### Definition

Let *H* be a Hilbert space,  $V \subseteq H$  a closed subspace, and

$$V^{\perp} = \{ z \in H : \forall y \in V, \langle z, y \rangle = 0 \}$$

be its orthogonal complement. Then, for every  $x \in H$ , there is a unique  $y \in V$  satisfying

$$||x - y|| = \min\{||x - y'|| : y' \in V\},\$$

and a unique  $z \in V^{\perp}$  such that x = y + z. The map  $P_V : H \to V$ ,  $P_V x = y$  is the *orthogonal projection* on *V*.

If  $\{v_n\}$  is an orthonormal basis for V, then  $P_V$  can be expressed as

$$\forall x \in H, \quad P_V x = \sum_n \langle x, v_n \rangle v_n.$$

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Can we make tight frames for  $H = \mathbb{F}^d$  ( $\mathbb{F} = \mathbb{R}$  or  $\mathbb{C}$ ) with prescribed redundancy?

Yes. Take an  $N \times N$  unitary matrix U, and choose any d columns of it to form an  $N \times d$  matrix L. Then,  $L^*L = I$ , which means, the rows of L form a 1-tight frame for  $\mathbb{F}^d$ .

How about FUNTFs?

Yes, we shall explain how to generate FUNTFs by using the frame potential.



If  $\{e_n\}_{n=1}^N$  is an A-tight frame for  $\mathbb{F}^d$ , and *L* is its Bessel map, then  $L^*L = AI$ , i.e., the set of the columns of L,  $\{c_1, \ldots, c_d\}$  is a  $\sqrt{A}$ -normed orthogonal set in  $\mathbb{F}^N$ . Let  $V = span\{c_1, \ldots, c_d\}$ , and let  $\{c_{d+1}, \ldots, c_N\}$  be a  $\sqrt{A}$ -normed orthogonal basis for  $V^{\perp}$ . Then, the matrix

$$U=A^{-1/2}[c_1\ldots c_N]$$

is a unitary matrix, since its columns give an ONB for  $\mathbb{F}^d$ . Then, the rows of U also give an ONB for  $\mathbb{F}^d$ . Let  $\tilde{e}_k$  be the *k*th row of  $A^{1/2}U$ . Then,

$$P(x[1],\ldots x[N]) = (x[1],\ldots,x[d]).$$



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#### Theorem (Naimark)

Let *H* be a *d*-dimensional Hilbert space,  $\{e_n\}_{n=1}^N$  be an *A*-tight frame for *H*. Then there exists an *N*-dimensional Hilbert space  $\widetilde{H}$ , and orthogonal *A*-normed set  $\{\widetilde{e}_n\}_{n=1}^N \subseteq \widetilde{H}$  such that

$$P_H \widetilde{e}_n = e_r$$

where  $P_H$  is the orthogonal projection onto H.



# The geometry of finite tight frames

- We saw the vertices of platonic solids are FUNTFs.
- However, points that constitute FUNTFs do not have to be equidistributed, e.g., ONBs and Grassmanian frames.
- FUNTFs can be characterized as minimizers of a frame potential function (with Fickus) analogous to Coulomb's Law.



$$F: S^{d-1} imes S^{d-1} \setminus D \longrightarrow \mathbb{R}^d$$

$$P: S^{d-1} \times S^{d-1} \setminus D \longrightarrow \mathbb{R},$$

where  $P(a, b) = p(||a - b||), \quad p'(x) = -xf(x)$ 

Coulomb force

$$CF(a,b) = (a-b)/||a-b||^3$$
,  $f(x) = 1/x^3$ 

Frame force

$$FF(a,b) = \langle a,b \rangle (a-b), \quad f(x) = 1 - x^2/2$$

Total potential energy for the frame force

$$TFP(\{x_n\}) = \sum_{m=1}^{N} \sum_{n=1}^{N} |\langle x_m, x_n \rangle|^2$$



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#### Theorem

Let  $N \le d$ . The minimum value of *TFP*, for the frame force and *N* variables, is *N*; and the *minimizers* are precisely the orthonormal sets of *N* elements for  $\mathbb{R}^d$ .

Let  $N \ge d$ . The minimum value of *TFP*, for the frame force and *N* variables, is  $N^2/d$ ; and the *minimizers* are precisely the FUNTFs of *N* elements for  $\mathbb{R}^d$ .

#### Problem

Find FUNTFs analytically, effectively, computationally.



Suppose we want to construct a FUNTF for  $\mathbb{F}^d$ .

If 𝔅 = 𝔅, Let (x<sub>1</sub>, x<sub>2</sub>,..., x<sub>N</sub>) denote a point in 𝔅<sup>Nd</sup>, where each x<sub>k</sub> ∈ 𝔅<sup>d</sup>. The solutions of the following constrained minimization problem are FUNTFs.

minimize 
$$TFP(x_1, x_2, \dots, x_N) = \sum_{m=1}^{N} \sum_{n=1}^{N} |\langle x_m, x_n \rangle|^2$$
 (1)  
subject to  $||x_n||^2 = 1, \quad \forall n = 1, \dots, N.$ 

If we view TFP as a function from  $\mathbb{R}^{Nd}$  into  $\mathbb{R}$ , then it is twice differentiable in each argument, so are the constraints. We can solve this problem numerically, e.g., by using Conjugate Gradient minimization algorithm.

If 𝔅 = 𝔅, we let (*Re*(*x*<sub>1</sub>), *Im*(*x*<sub>1</sub>),..., *Re*(*x<sub>N</sub>*), *Im*(*x<sub>N</sub>*)) denote a point in ℝ<sup>2Nd</sup>, view TFP as a function from ℝ<sup>2Nd</sup> into ℝ, and solve (1) as in the real case.

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# Björck CAZAC codes and ambiguity function comparisons

# Björck CAZAC codes and ambiguity function comparisons



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# Legendre symbol

Let N be a prime and (k, N) = 1.

- ▶ *k* is a quadratic residue mod *N* if  $x^2 = k \pmod{N}$  has a solution.
- ▶ k is a quadratic non-residue mod N if x<sup>2</sup> = k (mod N) has no solution.
- The Legendre symbol:

$$\begin{pmatrix} \frac{k}{N} \end{pmatrix} = \begin{cases} 1, & \text{if } k \text{ is a quadratic residue mod } N, \\ -1, & \text{if } k \text{ is a quadratic non-residue mod } N. \end{cases}$$

The diagonal of the product table of  $\mathbb{Z}_N$  gives values  $k \in \mathbb{Z}$  which are squares. As such we can program Legendre symbol computation.

Example: 
$$N = 7$$
.  $(\frac{k}{N}) = 1$  if  $k = 1, 2, 4$ .

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# Definition

Let N be a prime number. A Björck CAZAC sequence of length N is

$$u[k] = e^{i\theta_N(k)}, \quad k = 0, 1, \dots, N-1,$$

where, for  $N = 1 \pmod{4}$ ,

$$\theta_N(k) = \arccos\left(\frac{1}{1+\sqrt{N}}\right)\left(\frac{k}{N}\right),$$

and, for  $N = 3 \pmod{4}$ ,

$$\theta_N(k) = \frac{1}{2} \arccos\left(\frac{1-N}{1+N}\right) \left[\left(1-\delta_k\right)\left(\frac{k}{N}\right)+\delta_k\right].$$

 $\delta_k$  is Kronecker delta and  $\left(\frac{k}{N}\right)$  is Legendre symbol.

# Quadratic and Björck ambiguity comparison

- Waveforms associated to Chu-Zadoff and P4 CAZACs are known for their low sidelobes at zero Doppler shift, but their ambiguity functions exhibit strong coupling in the time-frequency plane.
- Waveforms associated to Björck CAZACs can more effectively decouple the effect of time and frequency shifts. However, at zero Doppler shift, their sidelobe behavior is less desirable than quadratic phase CAZACs.
- These differences led to our concatenation idea.





A concatenation of partial CAZACs u and v is w = Mix(r%, u, v) defined as

$$w[m] = u[m], \text{ if } m = 0, \dots, M$$

and

$$w[m] = v[m]$$
, if  $m = M + 1, ..., N - 1$ ,

where *M* is the nearest integer to  $r \times N/100$ .

► We show how the ambiguity function can be improved by concatenation of partial CAZACs belonging to two different families. The best choice is obtained with r = 50.



### Example

#### Ambiguity function of a partial concatenation.



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# Diversity by averaging technique

- Shifting Wiener CAZACs leads to the same type of discrete aperiodic ambiguity function, i.e., |A<sub>a</sub>(u(· − k<sub>0</sub>))| = |A<sub>a</sub>(u)|.
- Discrete aperiodic ambiguity functions of shifted Björck CAZACs exhibit diversity in both the size and location of their sidelobes.
- New families of CAZAC sequences are developed by an averaging technique based on shifting Björck CAZAC sequences.
- This technique is exploited using non-coherent processing (averaging absolute values) in order to achieve lower sidelobe levels.

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The discrete aperiodic ambiguity function



Applications

# Shapiro-Rudin polynomials



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Norbert Wiener Center The construction of perfect autocorrelation codes

The Shapiro-Rudin polynomials, P<sub>n</sub>(t), Q<sub>n</sub>(t), n = 0, 1, 2, ..., are defined recursively in the following manner. For t ∈ ℝ/Z,

$$P_0(t) = Q_0(t) = 1,$$
  

$$P_{n+1}(t) = P_n(t) + e^{2\pi i 2^n t} Q_n(t),$$
  

$$Q_{n+1}(t) = P_n(t) - e^{2\pi i 2^n t} Q_n(t).$$

- The number of terms in the  $n^{th}$  polynomial,  $P_n(t)$  or  $Q_n(t)$ , is  $2^n$ .
- Thus, the coefficients of each polynomial can be represented as a finite sequence of length 2<sup>n</sup> of (±1)s.



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### Golay complementary pairs

• For any sequence  $z = \{z_k\}_{k=0}^{n-1} \subseteq \mathbb{C}$  and for any  $m \in \{0, 1, ..., n-1\}$ , the  $m^{th}$  aperiodic autocorrelation coefficient,  $A_z(m)$ , is defined as

$$A_z(m) = \sum_{j=0}^{n-1-m} z_j \overline{z_{m+j}}.$$

• Two sequences,  $p = \{p_k\}_{k=0}^{n-1}$ ,  $q = \{q_k\}_{k=0}^{n-1} \subseteq \mathbb{C}$ , are a *Golay* complementary pair if  $A_p(0) + A_q(0) \neq 0$ , and,

$$\forall m = 1, 2, ..., n - 1, \qquad A_p(m) + A_q(m) = 0.$$

• For each *n*, the coefficients of *P<sub>n</sub>* and *Q<sub>n</sub>*, resp., are a Golay complementary pair.

### Cusps

- A parametrized curve  $\gamma : \mathbb{R} \to \mathbb{R}^2$ , defined by  $\gamma(t) = (u(t), v(t))$ , has a *non-regular point* at  $t = t_0$  if  $\frac{du}{dt}|_{t=t_0} = \frac{dv}{dt}|_{t=t_0} = 0$ . Otherwise,  $t_0$  is a *regular point*.
- A non-regular point  $t_0$  gives rise to a *quadratic cusp* for  $\gamma$  if  $\left(\frac{d^2 u}{dt^2}|_{t=t_0}, \frac{d^2 v}{dt^2}|_{t=t_0}\right) \neq (0,0).$
- A non-regular point  $t_0$  gives rise to an *ordinary cusp* if it gives rise to a quadratic cusp, and  $\left(\frac{d^2u}{dt^2}|_{t=t_0}, \frac{d^2v}{dt^2}|_{t=t_0}\right)$  and  $\left(\frac{d^3u}{dt^3}|_{t=t_0}, \frac{d^3v}{dt^3}|_{t=t_0}\right)$  are linearly independent vectors of the real vector space  $\mathbb{R}^2$ .
- Let P(z) = z<sup>2</sup> − 2z on C, and define γ(t) = P(e<sup>2πit</sup>). Then, γ has a non-regular point at t = t<sub>0</sub> and gives rise to a quadratic cusp there.

#### Theorem

a. For each  $n \in \mathbb{N}$ , the parametrization  $(Re(P_{2n}(t)), Im(P_{2n}(t)))$ gives rise to a quadratic cusp at  $(2^n, 0)$ , i.e., when t = 0. b. Further, neither  $(Re(P_{2n+1}(t)), Im(P_{2n+1}(t)))$  nor  $(Re(Q_n(t)), Im(Q_n(t)))$  gives rise to a cusp when t = 0.

#### Remark

The Theorem does not contradict the fact that  $P_{2n} : \mathbb{R} \longrightarrow \mathbb{C}$  is infinitely differentiable as a 1-periodic polynomial on  $\mathbb{R}$ .



### Graphs of $P_n(t)$ and $Q_n(t)$ for n=1,2,3,4

Graphical parametrizations of  $P_n(t)$  and  $Q_n(t)$  by means of  $(Re(P_n(t)), Im(P_n(t)))$  and  $(Re(Q_n(t)), Im(Q_n(t)))$  for n = 1, 2, 3, 4.







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# A vector-valued ambiguity function



Norbert Wiener Center The construction of perfect autocorrelation codes

### Outline

#### Problem and goal

#### 2 Frames

3 Multiplication problem and  $A_p^1$ 

**5**  $A_p^d(u)$  for DFT frames

#### 6 Figure





### Background

- Originally, our problem was to construct libraries of phase-coded waveforms v parameterized by design variables, for communications and radar.
- A goal was to achieve diverse ambiguity function behavior of *v* by defining new classes of quadratic phase and number theoretic perfect autocorrelation codes *u* with which to define *v*.
- A realistic more general problem was to construct vector-valued waveforms *v* in terms of vector-valued perfect autocorrelation codes *u*. Such codes are relevant in light of vector sensor and MIMO capabilities and modeling.
- Example: Discrete time data vector *u*(*k*) for a *d*-element array,

$$k \mapsto u(k) = (u_0(k), \ldots, u_{d-1}(k)) \in \mathbb{C}^d.$$

We can have  $\mathbb{R}^N \to GL(d, \mathbb{C})$ , or even more general.

### General problem and STFT theme

- Establish the theory of vector-valued ambiguity functions to estimate v in terms of ambiguity data.
- First, establish this estimation theory by defining the discrete periodic vector-valued ambiguity function in a natural way.
- Mathematically, this natural way is to formulate the discrete periodic vector-valued ambiguity function in terms of the Short Time Fourier Transform (STFT).



### STFT and ambiguity function

#### Short time Fourier transform - STFT

• The narrow band cross-correlation ambiguity function of v, w defined on  $\mathbb R$  is

$$A(\mathbf{v},\mathbf{w})(t,\gamma) = \int_{\mathbb{R}} \mathbf{v}(\mathbf{s}+t) \overline{\mathbf{w}(\mathbf{s})} e^{-2\pi i \mathbf{s} \gamma} d\mathbf{s}.$$

- *A*(*v*, *w*) is the STFT of *v* with window *w*.
- The narrow band radar ambiguity function A(v) of v on  $\mathbb{R}$  is

$$\begin{aligned} \mathsf{A}(\mathsf{v})(t,\gamma) &= \int_{\mathbb{R}} \mathsf{v}(s+t)\overline{\mathsf{v}(s)}e^{-2\pi i s \gamma} ds \\ &= e^{\pi i t \gamma} \int_{\mathbb{R}} \mathsf{v}\left(s+\frac{t}{2}\right) \overline{\mathsf{v}\left(s-\frac{t}{2}\right)} e^{-2\pi i s \gamma} ds, \text{ for } (t,\gamma) \in \mathbb{R}^{2}. \end{aligned}$$

#### Goal

- Let *v* be a phase coded waveform with *N* lags defined by the code *u*.
- Let *u* be *N*-periodic, and so *u* : Z<sub>N</sub> → C, where Z<sub>N</sub> is the additive group of integers modulo *N*.
- The discrete periodic ambiguity function  $A_p(u) : \mathbb{Z}_N \times \mathbb{Z}_N \longrightarrow \mathbb{C}$  is

$$A_{p}(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} u(m+k)\overline{u(k)}e^{-2\pi i k n/N}$$

#### Goal

Given a vector valued *N*-periodic code  $u : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$ , construct the following in a meaningful, computable way:

- Generalized C-valued periodic ambiguity function
   A<sup>1</sup><sub>D</sub>(u) : Z<sub>N</sub> × Z<sub>N</sub> → C
- $\mathbb{C}^d$ -valued periodic ambiguity function  $A^d_p(u) : \mathbb{Z}_N \times \mathbb{Z}_N \longrightarrow \mathbb{C}^d$

The STFT is the *guide* and the *theory of frames* is the technology to the Applications obtain the goal.

#### Problem and goal

#### 2 Frames

3 Multiplication problem and  $A_p^1$ 

#### 

**5**  $A_p^d(u)$  for DFT frames

#### 6 Figure





### **Multiplication problem**

• Given 
$$u : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$$
.

• If 
$$d = 1$$
 and  $e_n = e^{2\pi i n/N}$ , then

$$A_{\rho}(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} \langle u(m+k), u(k) \boldsymbol{e}_{nk} \rangle.$$

#### Multiplication problem

To characterize sequences  $\{E_k\} \subseteq \mathbb{C}^d$  and multiplications \* so that

$$egin{aligned} \mathcal{A}^1_{
ho}(u)(m,n) &= rac{1}{N}\sum_{k=0}^{N-1} \langle u(m+k), u(k) * \mathcal{E}_{nk} 
angle \in \mathbb{C} \end{aligned}$$

is a meaningful and well-defined *ambiguity function*. This formula is clearly motivated by the STFT.

for Harmonic Analysis and Application

There is a natural way to address the multiplication problem motivated by the fact that  $e_m e_n = e_{m+n}$ . To this end, we shall make the *ambiguity function assumptions*:

- $\exists \{E_k\}_{k=0}^{N-1} \subseteq \mathbb{C}^d$  and a multiplication \* such that  $E_m * E_n = E_{m+n}$  for  $m, n \in \mathbb{Z}_N$ ;
- $\{E_k\}_{k=0}^{N-1} \subseteq \mathbb{C}^d$  is a tight frame for  $\mathbb{C}^d$ ;
- $*: \mathbb{C}^d \times \mathbb{C}^d \longrightarrow \mathbb{C}^d$  is bilinear, in particular,

$$\left(\sum_{j=0}^{N-1} c_j E_j\right) * \left(\sum_{k=0}^{N-1} d_k E_k\right) = \sum_{j=0}^{N-1} \sum_{k=0}^{N-1} c_j d_k E_j * E_k.$$



- Let {*E<sub>j</sub>*}<sup>*N*-1</sup> ⊆ ℂ<sup>*d*</sup> satisfy the three ambiguity function assumptions.
- Given  $u, v : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$  and  $m, n \in \mathbb{Z}_N$ .
- Then, one calculates

$$u(m) * v(n) = \frac{d^2}{N^2} \sum_{j=0}^{N-1} \sum_{s=0}^{N-1} \langle u(m), E_j \rangle \langle v(n), E_s \rangle E_{j+s}.$$



Problem and goal

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## $A_{\rho}^{1}(u)$ for DFT frames

- Let {E<sub>j</sub>}<sup>N-1</sup> ⊆ C<sup>d</sup> satisfy the three ambiguity function assumptions.
- Further, assume that  $\{E_j\}_{j=0}^{N-1}$  is a DFT frame, and let *r* designate a fixed column.
- Without loss of generality, choose the first *d* columns of the  $N \times N$  DFT matrix.
- Then, one calculates

$$E_m * E_n(r) = \frac{d^2}{N^2} \sum_{j=0}^{N-1} \sum_{s=0}^{N-1} \langle E_m, E_j \rangle \langle E_n, E_s \rangle E_{j+s}(r).$$
$$= \frac{e_{(m+n)r}}{\sqrt{d}} = E_{m+n}(r).$$

- Thus, for DFT frames, ∗ is componentwise multiplication in C<sup>d</sup> with a factor of √d.
- In this case  $A^1_p(u)$  is well-defined for  $u : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$  by

$$\begin{aligned} A_p^1(u)(m,n) &= \frac{1}{N} \sum_{k=0}^{N-1} \langle u(m+k), u(k) * E_{nk} \rangle \\ &= \frac{d}{N^2} \sum_{k=0}^{N-1} \sum_{j=0}^{N-1} \langle E_j, u(k) \rangle \langle u(m+k), E_{j+nk} \rangle. \end{aligned}$$



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### Remark

- In the previous DFT example, \* is intrinsically related to the "addition" defined on the indices of the frame elements, viz.,  $E_m * E_n = E_{m+n}$ .
- Alternatively, we could have  $E_m * E_n = E_{m \bullet n}$  for some function
  - :  $\mathbb{Z}_N \times \mathbb{Z}_N \longrightarrow \mathbb{Z}_N$ , and, thereby, we could use frames which are not FUNTFs.
- Given a bilinear multiplication \* : C<sup>d</sup> × C<sup>d</sup> → C<sup>d</sup>, we can find a frame {E<sub>j</sub>}<sub>j</sub> and an index operation with the E<sub>m</sub> \* E<sub>n</sub> = E<sub>m•n</sub> property.
- If 

   is the multiplication for a group, possibly non-abelian and/or infinite, we may reverse the process and find a FUNTF and bilinear multiplication \* with the E<sub>m</sub> \* E<sub>n</sub> = E<sub>m•n</sub> property.

## $A_{\rho}^{1}(u)$ for cross product frames

- Take \* : C<sup>3</sup> × C<sup>3</sup> → C<sup>3</sup> to be the cross product on C<sup>3</sup> and let {*i*, *j*, *k*} be the standard basis.
- i \* j = k, j \* i = -k, k \* i = j, i \* k = -j, j \* k = i, k \* j = -i,  $i * i = j * j = k * k = 0. \{0, i, j, k, -i, -j, -k, \}$  is a tight frame for  $\mathbb{C}^3$  with frame constant 2. Let  $E_0 = 0, E_1 = i, E_2 = j, E_3 = k, E_4 = -i, E_5 = -j, E_6 = -k.$
- The index operation corresponding to the frame multiplication is the non-abelian operation  $\bullet: \mathbb{Z}_7 \times \mathbb{Z}_7 \longrightarrow \mathbb{Z}_7$ , where  $1 \bullet 2 = 3, 2 \bullet 1 = 6, 3 \bullet 1 = 2, 1 \bullet 3 = 5, 2 \bullet 3 = 1, 3 \bullet 2 = 4, 1 \bullet 1 = 2 \bullet 2 = 3 \bullet 3 = 0, n \bullet 0 = 0 \bullet n = 0, 1 \bullet 4 = 0, 1 \bullet 5 = 6, 1 \bullet 6 = 2, 4 \bullet 1 = 0, 5 \bullet 1 = 3, 6 \bullet 1 = 5, 2 \bullet 4 = 3, 2 \bullet 5 = 0$ , etc.
- The three ambiguity function assumptions are valid and so we can write the cross product as

$$u \times v = u * v = \frac{1}{2^2} \sum_{s=1}^{6} \sum_{t=1}^{6} \langle u, E_s \rangle \langle v, E_t \rangle E_{s \bullet t}.$$

• Consequently,  $A_{\rho}^{1}(u)$  can be well-defined.

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## Vector-valued ambiguity function $A_p^d(u)$

- Let {E<sub>j</sub>}<sup>N-1</sup> ⊆ C<sup>d</sup> satisfy the three ambiguity function assumptions.
- Given  $u : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$ .
- The following definition is clearly motivated by the STFT.

#### Definition

$$A^d_p(u):\mathbb{Z}_N imes\mathbb{Z}_N\longrightarrow\mathbb{C}^d$$
 is defined by

$$A_{\rho}^{d}(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} u(m+k) * \overline{u(k)} * \overline{E_{nk}}.$$

John J. Benedetto and Jeffrey J. Donatelli Frames and a vector-valued ambiguity function

Problem and goal

#### 2 Frames

- 3 Multiplication problem and  $A_p^1$
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## STFT formulation of $A_p(u)$

The discrete periodic ambiguity function of *u* : Z<sub>N</sub> → C can be written as

$$A_{p}(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} \langle \tau_{m} u(k), F^{-1}(\tau_{n} \hat{u})(k) \rangle,$$

where  $\tau_{(m)}u(k) = u(m+k)$  is translation by *m* and  $F^{-1}(u)(k)) = \check{u}(k)$  is Fourier inversion.

- As such we see that  $A_{\rho}(u)$  has the form of a STFT.
- We shall develop a vector-valued DFT theory to *verify* (not just *motivate*) that  $A_p^d(u)$  is an STFT in the case  $\{E_k\}_{k=0}^{N-1}$  is a DFT frame for  $\mathbb{C}^d$ .

#### Definition

Given  $u : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$ , and let  $\{E_k\}_{k=0}^{N-1}$  be a DFT frame for  $\mathbb{C}^d$ . The *vector-valued discrete Fourier transform* of *u* is

$$\forall n \in \mathbb{Z}_N, \quad F(u)(n) = \hat{u}(n) = \sum_{m=0}^{N-1} u(m) * E_{mn},$$

where \* is pointwise (coordinatewise) multiplication.



### Vector-valued Fourier inversion theorem

- Inversion process for the vector-valued case is analogous to the 1-dimensional case.
- We must define a new multiplication in the frequency domain to avoid divisibility problems.
- Define the weighted multiplication  $(*) : \mathbb{C}^d \times \mathbb{C}^d \longrightarrow \mathbb{C}^d$  by  $u(*)v = u * v * \omega$  where  $\omega = (\omega_1, \dots, \omega_d)$  has the property that each  $\omega_n = \frac{1}{\#\{m \in \mathbb{Z}_N: mn=0\}}$ .
- For the following theorem assume *d* << *N* or *N* prime.

#### Theorem - Vector-valued Fourier inversion

The vector valued Fourier transform *F* is an isomorphism from  $\ell^2(\mathbb{Z}_N)$  to  $\ell^2(\mathbb{Z}_N, \omega)$  with inverse

$$\forall m \in \mathbb{Z}_N, \quad F^{-1}(m) = u(m) = \frac{d}{N} \sum_{n=0}^{N-1} \hat{u}(n) * E_{-mn} * \omega.$$

N prime implies F is unitary.

## $A_p^d(u)$ as an STFT

- Given  $u, v : \mathbb{Z}_N \longrightarrow \mathbb{C}^d$ , and let  $\{E_k\}_{k=0}^{N-1}$  be a DFT frame for  $\mathbb{C}^d$ .
- $u * \overline{v}$  denotes pointwise (coordinatewise) multiplication with a factor of  $\sqrt{d}$ .
- We compute

$$A_p^d(u)(m,n) = \frac{1}{N} \sum_{k=0}^{N-1} (\tau_m u(k)) * \overline{F^{-1}(\tau_n \hat{u})(k)}.$$

 Thus, A<sup>d</sup><sub>p</sub>(u) is compatible with point of view of defining a vector-valued ambiguity function in the context of the STFT. Problem and goal

#### 2 Frames

3 Multiplication problem and  $A_p^1$ 

**5**  $A_p^d(u)$  for DFT frames

#### 6 Figure







- If (G, •) is a finite group with representation ρ : G → GL(C<sup>d</sup>), then there is a frame {E<sub>n</sub>}<sub>n∈G</sub> and bilinear multiplication,
   \* : C<sup>d</sup> × C<sup>d</sup> → C<sup>d</sup>, such that E<sub>m</sub> \* E<sub>n</sub> = E<sub>m•n</sub>. Thus, we can develop A<sup>d</sup><sub>ρ</sub>(u) theory in this setting.
- Analyze ambiguity function behavior for (phase-coded) vector-valued waveforms *v* : ℝ → ℂ<sup>d</sup>, defined by *u* : ℤ<sub>N</sub> → ℂ<sup>d</sup> as

$$v = \sum_{k=0}^{N-1} u(k) \mathbb{1}_{[kT,(k+1)T)},$$

in terms of  $A_{p}^{d}(u)$ . (See Figure)

aveform design

# Computation of $u : \mathbb{Z}_N \to \mathbb{C}^d$ from ambiguity

▶ CAZAC and waveform computation of  $u : \mathbb{Z}_N \to \mathbb{C}^d$  from A(u): Let  $A_u$  be the  $N \times N$  matix, (A(u)(m, n)). Define the  $N \times N$  matrix  $U = (U_{i,j})$ , where  $U_{i,j} = \langle u(i+j), u(j) \rangle$ . Then

 $U = A_u D_N$ , where  $D_N = DFT$  matrix.

- ▶ Let d = 1. Note that  $U_{k,0} = u(k)\overline{u(0)}$ . Hence, if we know the values of the ambiguity function, and, thus, the ambiguity function matrix  $A_u$ , then the sequence u, which generates it, can be computed as long as  $u(0) \neq 0$ . In fact, if u(0) = 1 then  $u(k) = (A_u D_N)(k, 0)$ .
- Similar result for  $A_V(u)$  using our vector-valued Fourier analysis.
- ▶ Now we can address the classical *radar ambiguity problem*: Find the structure of all  $z : \mathbb{Z}_N \to \mathbb{C}^d$  for which |A(u)| = |A(z)| on  $X \subseteq \mathbb{Z}_N \times \mathbb{Z}_N$ .

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## **Quantization Methods**



Given  $u_0$  and  $\{x_n\}_{n=1}$ 

$$u_n = u_{n-1} + x_n - q_n$$
  
 $q_n = Q(u_{n-1} + x_n)$ 



First Order  $\Sigma\Delta$ 



### A quantization problem

**Qualitative Problem** Obtain *digital* representations for class *X*, suitable for storage, transmission, recovery. **Quantitative Problem** Find dictionary  $\{e_n\} \subseteq X$ :

• Sampling [continuous range  $\mathbb{K}$  is not digital]

 $\forall x \in X, \quad x = \sum x_n e_n, \quad x_n \in \mathbb{K}.$ 

2 Quantization. Construct finite alphabet A and

 $Q: X \to \{\sum q_n e_n : q_n \in \mathcal{A} \subseteq \mathbb{K}\}$ 

such that  $|x_n - q_n|$  and/or ||x - Qx|| small.

#### Methods

Fine quantization, e.g., PCM. Take  $q_n \in A$  close to given  $x_n$ . Reasonable in 16-bit (65,536 levels)digital audio. Coarse quantization, e.g.,  $\Sigma \Delta$ . Use fewer bits to exploit redundancy. SRQP

$$\mathcal{A}_{K}^{\delta} = \{(-K+1/2)\delta, (-K+3/2)\delta, \dots, (-1/2)\delta, (1/2)\delta, \dots, (K-1/2)\delta\}$$



Replace 
$$x_n \leftrightarrow q_n = \arg\{\min |x_n - q| : q \in \mathcal{A}_{\mathcal{K}}^{\delta}\}$$
. Then

$$(PCM) \qquad \tilde{x} = \frac{d}{N} \sum_{n=1}^{N} q_n e_n$$

satisfies

$$\|\boldsymbol{x}-\tilde{\boldsymbol{x}}\| \leq \frac{d}{N} \|\sum_{n=1}^{N} (\boldsymbol{x}_n - \boldsymbol{q}_n) \boldsymbol{e}_n\| \leq \frac{d}{N} \frac{\delta}{2} \sum_{n=1}^{N} \|\boldsymbol{e}_n\| = \frac{d}{2} \delta.$$

Not good!

#### Bennett's white noise assumption

Assume that  $(\eta_n) = (x_n - q_n)$  is a sequence of independent, identically distributed random variables with mean 0 and variance  $\frac{\delta^2}{12}$ . Then the mean square error (MSE) satisfies

$$\mathsf{MSE} = E \| x - \tilde{x} \|^2 \le \frac{d}{12A} \, \delta^2 = \frac{(d\delta)^2}{12N}$$

enter

Let  $x = (\frac{1}{3}, \frac{1}{2}), E_7 = \{(\cos(\frac{2n\pi}{7}), \sin(\frac{2n\pi}{7}))\}_{n=1}^7$ . Consider quantizers with  $A = \{-1, 1\}$ .



## $A_1^2 = \{-1, 1\}$ and $E_7$


## $A_1^2 = \{-1, 1\}$ and $E_7$



# $A_1^2 = \{-1, 1\}$ and $E_7$



Let  $F = \{e_n\}_{n=1}^N$  be a frame for  $\mathbb{R}^d$ ,  $x \in \mathbb{R}^d$ . Define  $x_n = \langle x, e_n \rangle$ . Fix the ordering p, a permutation of  $\{1, 2, ..., N\}$ . Quantizer alphabet  $\mathcal{A}_{\mathcal{K}}^{\delta}$ Quantizer function  $Q(u) = \arg\{\min | u - q| : q \in \mathcal{A}_{\mathcal{K}}^{\delta}\}$ Define the first-order  $\Sigma \wedge$  quantizer with ordering p and with

Define the *first-order*  $\Sigma \Delta$  *quantizer* with ordering *p* and with the quantizer alphabet  $\mathcal{A}_{\mathcal{K}}^{\delta}$  by means of the following recursion.

$$U_n - U_{n-1} = X_{p(n)} - q_n$$
  
 $q_n = Q(u_{n-1} + x_{p(n)})$ 

where  $u_0 = 0$  and n = 1, 2, ..., N.



## Sigma-Delta quantization – background

- History from 1950s.
- Treatises of Candy, Temes (1992) and Norsworthy, Schreier, Temes (1997).
- PCM for finite frames and ΣΔ for PW<sub>Ω</sub>: Bølcskei, Daubechies, DeVore, Goyal, Gunturk, Kovačevič, Thao, Vetterli.
- Combination of  $\Sigma\Delta$  and finite frames: Powell, Yılmaz, and B.
- Subsequent work based on this ΣΔ finite frame theory: Bodman and Paulsen; Boufounos and Oppenheim; Jimenez and Yang Wang; Lammers, Powell, and Yılmaz.
- Genuinely apply it.



## Stability

The following stability result is used to prove error estimates.

#### Proposition

If the frame coefficients  $\{x_n\}_{n=1}^N$  satisfy

$$|x_n| \leq (K-1/2)\delta, \quad n=1,\cdots,N,$$

then the state sequence  $\{u_n\}_{n=0}^N$  generated by the first-order  $\Sigma \Delta$  quantizer with alphabet  $\mathcal{A}_K^{\delta}$  satisfies  $|u_n| \leq \delta/2, n = 1, \dots, N$ .

• The first-order  $\Sigma\Delta$  scheme is equivalent to

$$u_n = \sum_{j=1}^n x_{p(j)} - \sum_{j=1}^n q_j, \quad n = 1, \cdots, N.$$

Stability results lead to tiling problems for higher order schemes.

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#### Definition

Let  $F = \{e_n\}_{n=1}^N$  be a frame for  $\mathbb{R}^d$ , and let p be a permutation of  $\{1, 2, ..., N\}$ . The variation  $\sigma(F, p)$  is

$$\sigma(F,p) = \sum_{n=1}^{N-1} \|e_{p(n)} - e_{p(n+1)}\|.$$



#### Theorem

Let  $F = \{e_n\}_{n=1}^N$  be an A-FUNTF for  $\mathbb{R}^d$ . The approximation

$$\tilde{x} = \frac{d}{N} \sum_{n=1}^{N} q_n e_{p(n)}$$

generated by the first-order  $\Sigma\Delta$  quantizer with ordering *p* and with the quantizer alphabet  $\mathcal{A}_{\mathcal{K}}^{\delta}$  satisfies

$$\|x-\tilde{x}\| \leq \frac{(\sigma(F,p)+1)d}{N} \frac{\delta}{2}$$

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Zimmermann and Goyal, Kelner, Kovačevic, Thao, Vetterli.

#### Definition

 $H = \mathbb{C}^d$ . An harmonic frame  $\{e_n\}_{n=1}^N$  for H is defined by the rows of the Bessel map L which is the complex N-DFT  $N \times d$  matrix with N - d columns removed.

 $H = \mathbb{R}^d$ , *d* even. The harmonic frame  $\{e_n\}_{n=1}^N$  is defined by the Bessel map *L* which is the  $N \times d$  matrix whose *n*th row is

$$e_n^N = \sqrt{\frac{2}{d}} \left( \cos(\frac{2\pi n}{N}), \sin(\frac{2\pi n}{N}), \dots, \cos(\frac{2\pi (d/2)n}{N}), \sin(\frac{2\pi (d/2)n}{N}) \right)$$

- Harmonic frames are FUNTFs.
- Let  $E_N$  be the harmonic frame for  $\mathbb{R}^d$  and let  $p_N$  be the identity permutation. Then

$$\forall N, \ \sigma(E_N, p_N) \leq \pi d(d+1).$$



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## Error estimate for harmonic frames

#### Theorem

Let  $E_N$  be the harmonic frame for  $\mathbb{R}^d$  with frame bound N/d. Consider  $x \in \mathbb{R}^d$ ,  $||x|| \le 1$ , and suppose the approximation  $\tilde{x}$  of x is generated by a first-order  $\Sigma \Delta$  quantizer as before. Then

$$\|x-\tilde{x}\|\leq rac{d^2(d+1)+d}{N} rac{\delta}{2}.$$

Hence, for harmonic frames (and all those with bounded variation),

$$\mathsf{MSE}_{\Sigma\Delta} \leq rac{C_d}{N^2} \, \delta^2.$$

• This bound is clearly superior asymptotically to

$$\mathsf{MSE}_{\mathsf{PCM}} = \frac{(d\delta)^2}{12N}.$$



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#### Theorem

The first order  $\Sigma\Delta$  scheme achieves the asymptotically optimal MSE<sub>PCM</sub> for harmonic frames.

The digital encoding

$$\mathsf{MSE}_{\mathsf{PCM}} = \frac{(d\delta)^2}{12N}$$

in PCM format leaves open the possibility that decoding (consistent nonlinear reconstruction, with additional numerical complexity this entails) could lead to

"MSE<sub>PCM</sub>" 
$$\ll O(\frac{1}{N}).$$

Goyal, Vetterli, Thao (1998) proved

$$ext{`MSE}_{ extsf{PCM}}^{ extsf{opt}} extsf{``} \sim rac{ ilde{C}_d}{N^2} \delta^2.$$



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# A comparison of $\Sigma\text{-}\Delta$ and PCM

Let 
$$x \in \mathbb{C}^d$$
,  $||x|| \leq 1$ .

#### Definition

- $q_{PCM}(x)$  is the sequence to which x is mapped by PCM.
- $q_{\Sigma\Delta}(x)$  is the sequence to which x is mapped by  $\Sigma\Delta$ .

$$ext{err}_{PCM}(x) = ||x - rac{d}{N}L^*q_{PCM}(x)||$$
  
 $ext{err}_{\Sigma\Delta}(x) = ||x - rac{d}{N}L^*q_{\Sigma\Delta}(x)||$ 

Fickus question: We shall analyze to what extent  $err_{\Sigma\Delta}(x) < err_{PCM}(x)$  beyond our results with Powell and Yilmaz.



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#### Definition

A function  $e : [a, b] \to \mathbb{C}^d$  is of *bounded variation (BV)* if there is a K > 0 such that for every  $a \le t_1 < t_2 < \cdots < t_N \le b$ ,

$$\sum_{n=1}^{N-1} \|e(t_n) - e(t_{n+1})\| \le K.$$

The smallest such *K* is denoted by  $|e|_{BV}$ , and defines a seminorm for the space of BV functions.



#### Theorem

Let  $e : [0, 1] \to \{x \in \mathbb{C}^d : ||x|| = 1\}$  be continuous function of bounded variation such that  $F_N = (e(n/N))_{n=1}^N$  is a FUNTF for  $\mathbb{C}^d$  for every *N*. Then,

$$\exists N_0 > 0 \text{ such that } \forall N \ge N_0 \text{ and } \forall 0 < \|x\| \le 1$$

$$\operatorname{err}_{\Sigma\Delta}(X) \leq \operatorname{err}_{PCM}(X).$$

Moreover, a lower bound for  $N_0$  is  $d(1 + |e|_{BV})/(\sqrt{d} - 1)$ .



#### Example (Roots of unity frames for $\mathbb{R}^2$ )

 $e_n^N = (\cos(2\pi n/N), \sin(2\pi n/N)).$ 

Here,  $e(t) = (\cos(2\pi t), \sin(2\pi t)),$  $M = |e|_{BV} = 2\pi, \lim \alpha_{F_N} = 2/\pi.$ 

#### Example (Real Harmonic Frames for $\mathbb{R}^{2k}$ )

$$e_n^N = \frac{1}{\sqrt{k}} (\cos(2\pi n/N), \sin(2\pi n/N), \dots, \cos(2\pi kn/N), \sin(2\pi kn/N)).$$
  
In this case,  $e(t) = \frac{1}{\sqrt{k}} (\cos(2\pi t), \sin(2\pi t), \dots, \cos(2\pi kt), \sin(2\pi kt)),$   
 $M = |e|_{BV} = 2\pi \sqrt{\frac{1}{d} \sum_{k=1}^{d} k^2}.$ 

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## Comparison of 2-bit PCM and 1-bit $\Sigma \Delta$



Red:  $err_{PCM}(x) < err_{\Sigma\Delta}(x)$ , Green:  $err_{PCM}(x) = err_{\Sigma\Delta}(x)$ 

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## Comparison of 2-bit PCM and 1-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(X)$ 

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## Comparison of 2-bit PCM and 1-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(X)$ 

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## Comparison of 3-bit PCM and 1-bit $\Sigma \Delta$

81st Roots of 1 frame, 3bit PCM vs 1bit  $\Sigma\Delta$ 



Red:  $err_{PCM}(x) < err_{\Sigma\Delta}(x)$ , Green:  $err_{PCM}(x) = err_{\Sigma\Delta}(x)$ 

## Comparison of 3-bit PCM and 1-bit $\Sigma \Delta$

101st Roots of 1 frame, 3bit PCM vs 1bit  $\Sigma\Delta$ 



Red:  $err_{PCM}(x) < err_{\Sigma\Delta}(x)$ , Green:  $err_{PCM}(x) = err_{\Sigma\Delta}(x)$ 

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## Comparison of 3-bit PCM and 1-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(X)$ 

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## Comparison of 3-bit PCM and 2-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(X)$ 

## Comparison of 3-bit PCM and 2-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(x)$ 

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## Comparison of 3-bit PCM and 2-bit $\Sigma \Delta$



**Red**:  $\operatorname{err}_{PCM}(x) < \operatorname{err}_{\Sigma\Delta}(x)$ , Green:  $\operatorname{err}_{PCM}(x) = \operatorname{err}_{\Sigma\Delta}(X)$ 

## Complex $\Sigma$ - $\Delta$ and Yang Wang's idea and algorithm

# Complex $\Sigma$ - $\Delta$ and Yang Wang's idea and algorithm

## **Complex** $\Sigma \Delta$ - Alphabet

Let  $K \in \mathbb{N}$  and  $\delta > 0$ . The *midrise* quantization alphabet is

$$\mathcal{A}_{K}^{\delta} = \left\{ \left(m + \frac{1}{2}\right)\delta + in\delta : m = -K, \dots, K-1, n = -K, \dots, K \right\}$$



**Figure:**  $\mathcal{A}_{K}^{\delta}$  for  $K = 3\delta$ .



Finite frames

## **Complex** $\Sigma \Delta$

The scalar uniform quantizer associated to  $\mathcal{A}_{\mathcal{K}}^{\delta}$  is

$$Q_{\delta}(a+ib) = \delta\left(rac{1}{2} + \left\lfloorrac{a}{\delta}
ight
floor + i\left\lfloorrac{b}{\delta}
ight
floor
ight),$$

where  $\lfloor x \rfloor$  is the largest integer smaller than *x*. For any z = a + ib with  $|a| \le K$  and  $|b| \le K$ , *Q* satisfies

$$|z-Q_{\delta}(z)|\leq \min_{\zeta\in \mathcal{A}_{\mathcal{K}}^{\delta}}|z-\zeta|.$$

Let  $\{x_n\}_{n=1}^N \subseteq \mathbb{C}$  and let *p* be a permutation of  $\{1, \ldots, N\}$ . Analogous to the real case, the first order  $\Sigma \Delta$  quantization is defined by the iteration

## Complex $\Sigma \Delta$

#### The following theorem is analogous to BPY

#### Theorem

Let  $F = \{e_n\}_{n=1}^N$  be a finite unit norm frame for  $\mathbb{C}^d$ , let p be a permutation of  $\{1, \ldots, N\}$ , let  $|u_0| \le \delta/2$ , and let  $x \in \mathbb{C}^d$  satisfy  $||x|| \le (K - 1/2)\delta$ . The  $\Sigma\Delta$  approximation error  $||x - \tilde{x}||$  satisfies

$$\|\boldsymbol{x} - \widetilde{\boldsymbol{x}}\| \leq \sqrt{2} \|\boldsymbol{S}^{-1}\|_{\mathrm{op}} \left( \sigma(\boldsymbol{F}, \boldsymbol{p}) \frac{\delta}{2} + |\boldsymbol{u}_N| + |\boldsymbol{u}_0| \right),$$

where  $S^{-1}$  is the inverse frame operator. In particular, if F is a FUNTF, then

$$\|\mathbf{x}-\widetilde{\mathbf{x}}\| \leq \sqrt{2} \frac{d}{N} \left( \sigma(F, p) \frac{\delta}{2} + |u_N| + |u_0| \right),$$

## **Complex** $\Sigma \Delta$

Let  $\{F_N\}$  be a family of FUNTFs, and  $p_N$  be a permutation of  $\{1, \ldots, N\}$ . Then the frame variation  $\sigma(F_N, p_N)$  is a function of *N*. If  $\sigma(F_N, p_N)$  is bounded, then

$$\|x - \widetilde{x}\| = \mathcal{O}(N^{-1})$$
 as  $N \to \infty$ .

Wang gives an upper bound for the frame variation of frames for  $\mathbb{R}^d$ , using the results from the Travelling Salesman Problem.

#### **Theorem YW**

Let  $S = \{v_j\}_{j=1}^N \subseteq [-\frac{1}{2}, \frac{1}{2}]^d$  with  $d \ge 3$ . There exists a permutation p of  $\{1, \ldots, N\}$  such that

$$\sum_{j=1}^{N-1} \|v_{\rho(j)} - v_{\rho(j+1)}\| \leq 2\sqrt{d+3}N^{1-\frac{1}{d}} - 2\sqrt{d+3}.$$

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## Complex $\Sigma \Delta$

#### Theorem

Let  $F = \{e_n\}_{n=1}^N$  be a FUNTF for  $\mathbb{R}^d$ ,  $|u_0| \le \delta/2$ , and let  $x \in \mathbb{R}^d$  satisfy  $||x|| \le (K - 1/2)\delta$ . Then, there exists a permutation p of  $\{1, 2, ..., N\}$  such that the approximation error  $||x - \tilde{x}||$  satisfies

$$\|x - \widetilde{x}\| \leq \sqrt{2}\delta d\left((1 - \sqrt{d+3})N^{-1} + \sqrt{d+3}N^{-\frac{1}{d}}\right)$$

This theorem guarantees that

$$\|x - \widetilde{x}\| \leq \mathcal{O}(N^{-rac{1}{d}})$$
 as  $N \to \infty$ 

for FUNTFs for  $\mathbb{R}^d$ .



# $\Sigma$ - $\Delta$ and analytic number theory



#### Even – odd



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$$E_{N} = \{e_{n}^{N}\}_{n=1}^{N}, e_{n}^{N} = (\cos(2\pi n/N), \sin(2\pi n/N)). \text{ Let } x = (\frac{1}{\pi}, \sqrt{\frac{3}{17}}).$$
$$x = \frac{d}{N} \sum_{n=1}^{N} x_{n}^{N} e_{n}^{N}, \quad x_{n}^{N} = \langle x, e_{n}^{N} \rangle.$$

Let  $\tilde{x}_N$  be the approximation given by the 1st order  $\Sigma \Delta$  quantizer with alphabet  $\{-1, 1\}$  and natural ordering.



## Improved estimates

 $E_N = \{e_n^N\}_{n=1}^N$ , *N*th roots of unity FUNTFs for  $\mathbb{R}^2$ ,  $x \in \mathbb{R}^2$ ,  $||x|| \le (K - 1/2)\delta$ .

Quantize 
$$x = \frac{d}{N} \sum_{n=1}^{N} x_n^N e_n^N, \quad x_n^N = \langle x, e_n^N \rangle$$

using 1st order  $\Sigma\Delta$  scheme with alphabet  $\mathcal{A}_{K}^{\delta}$ .

#### Theorem

If *N* is even and large then 
$$||x - \tilde{x}|| \le B_x \frac{\delta \log N}{N^{5/4}}$$
.

If *N* is odd and large then  $A_x \frac{\delta}{N} \le ||x - \tilde{x}|| \le B_x \frac{(2\pi+1)d}{N} \frac{\delta}{2}$ .

- The proof uses a theorem of Genterk (from complex or harmonic analysis); and Koksma and Erders-Turan inequalities and van der Corput lemma (from analytic number theory).
- The Theorem is true for harmonic frames for  $\mathbb{R}^d$ .

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## **Proof of Improved Estimates theorem**

If N is even and large then ||x - x̃|| ≤ B<sub>x</sub> δ log N/N<sup>5/4</sup>. If N is odd and large then A<sub>x</sub> δ/N ≤ ||x - x̃|| ≤ B<sub>x</sub> (2π+1)d/N<sup>5/4</sup>.
∀N, {e<sub>n</sub><sup>N</sup>}<sub>n=1</sub><sup>N</sup> is a FUNTF.

$$\begin{aligned} x - \widetilde{x}_{N} &= \frac{d}{N} \left( \sum_{n=1}^{N-2} v_{n}^{N} (f_{n}^{N} - f_{n+1}^{N}) + v_{N-1}^{N} f_{N-1}^{N} + u_{N}^{N} e_{N}^{N} \right) \\ f_{n}^{N} &= e_{n}^{N} - e_{n+1}^{N}, \quad v_{n}^{N} = \sum_{j=1}^{n} u_{j}^{N}, \quad \widetilde{u}_{n}^{N} = \frac{u_{n}^{N}}{\delta} \end{aligned}$$

• To bound  $v_n^N$ .



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#### Definition

The *discrepancy*  $D_N$  of a finite sequence  $x_1, \ldots, x_N$  of real numbers is  $D_N = D_N(x_1, \ldots, x_N) = \sup_{0 \le \alpha < \beta \le 1} \left| \frac{1}{N} \sum_{n=1}^N \mathbb{1}_{[\alpha,\beta)}(\{x_n\}) - (\beta - \alpha) \right|,$  where  $\{x\} = x - \lfloor x \rfloor$ .

#### Theorem(Koksma Inequality)

 $g: [-1/2, 1/2) \rightarrow \mathbb{R}$  of bounded variation and  $\{\omega_j\}_{j=1}^n \subset [-1/2, 1/2) \Longrightarrow$ 

$$\left|rac{1}{n}\sum_{j=1}^n g(\omega_j) - \int_{-rac{1}{2}}^{rac{1}{2}} g(t) \mathsf{d} t
ight| \leq \mathrm{Var}(oldsymbol{g}) \mathrm{Disc}\Big(\{\omega_j\}_{j=1}^n\Big).$$

With g(t) = t and  $\omega_j = \tilde{u}_j^N$ ,

$$|v_n^N| \leq n\delta \mathrm{Disc}\Big(\{\widetilde{u}_j^N\}_{j=1}^n\Big)$$


$$\exists \boldsymbol{\mathcal{C}} > \boldsymbol{0}, \forall \boldsymbol{\mathcal{K}}, \text{Disc}\Big(\{\widetilde{\boldsymbol{\mathcal{U}}}_n^N\}_{n=1}^j\Big) \leq \boldsymbol{\mathcal{C}}\bigg(\frac{1}{K} + \frac{1}{j}\sum_{k=1}^K \frac{1}{k}\bigg|\sum_{n=1}^j \boldsymbol{e}^{2\pi i k \widetilde{\boldsymbol{\mathcal{U}}}_n^N}\bigg|\bigg).$$

#### To approximate the exponential sum.



## Güntürk's Proposition (1)

 $\forall N, \exists X_N \in \mathcal{B}_{\Omega/N} \text{ such that }, \forall n = 0, \dots, N$ 

$$X_N(n) = u_n^N + c_n rac{\delta}{2}, \ c_n \in \mathbb{Z}$$

and,  $\forall t$ ,

$$\left|X_{N}'(t)-h\left(rac{t}{N}
ight)
ight|\leq Brac{1}{N}$$

## Bernstein's Inequality (2)

If  $x \in \mathcal{B}_{\Omega}$ , then  $\|x^{(r)}\|_{\infty} \leq \Omega^{r} \|x\|_{\infty}$ 

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$$\forall t, \left| X_N''(t) - \frac{1}{N} h'\left(\frac{t}{N}\right) \right| \leq B \frac{1}{N^2}$$

• 
$$\widehat{\mathcal{B}}_{\Omega} = \{ \mathcal{T} \in \mathcal{A}'(\widehat{\mathbb{R}}) : \operatorname{supp} \mathcal{T} \subseteq [-\Omega, \Omega] \}$$

• 
$$\mathcal{M}_{\Omega} = \{h \in \mathcal{B}_{\Omega} : h' \in L^{\infty}(\mathbb{R}) \text{ and all zeros of } h' \text{ on } [0,1] \text{ are simple} \}$$

• We assume  $\exists h \in \mathcal{M}_{\Omega}$  such that  $\forall N$  and  $\forall 1 \leq n \leq N$ ,  $h(n/N) = x_n^N$ .

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• Let *a*, *b* be integers with a < b, and let *f* satisfy  $f'' \ge \rho > 0$  on [a, b] or  $f'' \le -\rho < 0$  on [a, b]. Then

$$\Big|\sum_{n=a}^{b}e^{2\pi i f(n)}\Big| \leq \Big(\big|f'(b)-f'(a)\big|+2\Big)\Big(\frac{4}{\sqrt{\rho}}+3\Big).$$



•  $\forall \mathbf{0} < \alpha < \mathbf{1}, \exists N_{\alpha} \text{ such that } \forall N \geq N_{\alpha},$ 

$$\Big|\sum_{n=1}^{j} e^{2\pi i k \widetilde{u}_{n}^{N}}\Big| \leq B_{x} N^{\alpha} + B_{x} \frac{\sqrt{k} N^{1-\frac{\alpha}{2}}}{\sqrt{\delta}} + B_{x} \frac{k}{\delta}.$$
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Putting  $\alpha = 3/4$ ,  $K = N^{1/4}$  yields

$$\exists \widetilde{N} \text{ such that } \forall N \geq \widetilde{N}, \operatorname{Disc}\left(\{\widetilde{u}_{n}^{N}\}_{n=1}^{j}\right) \leq B_{x} \frac{1}{N^{\frac{1}{4}}} + B_{x} \frac{N^{\frac{3}{4}} \log(N)}{j}$$

#### Conclusion

$$\forall n = 1, \dots, N, \ |v_n^N| \le B_x \delta N^{\frac{3}{4}} \log N$$



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## Hadamard matrices and infinite CAZAC codes

# Hadamard matrices and infinite CAZAC codes



## Accomplishments

- Developed libraries of CAZAC codes parameterized by design variables, proven mathematically and made available by user friendly software (CAZAC Playstation).
- Refined and formulated new, large classes of quadratic phase CAZAC codes and introduced Björck CAZAC codes to achieve diverse discrete periodic ambiguity function behavior.
- Enhanced sidelobe suppression by averaging and mixing techniques for CAZAC codes.
- Constructed vector-valued CAZAC codes with frame properties. This was motivated by the fact that frames lead to robust/stable signal decompositions. Vector-valued CAZAC codes are relevant in light of vector sensor and MIMO capabilities.
- Established the theory of waveforms coded by finite Gabor systems, and made a quantitative comparison with the non-Gabor case (A. Bourouihiya).
- Proved preliminary mathematical results to estimate the number of essentially different CAZAC codes of length N.

## Transition and the future

 Our CAZAC software continues to be developed. This is ongoing work in order to develop a useful tool for the community. See

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www.math.umd.edu/~jjb/cazac/
```

• We shall analyze the wideband radar ambiguity function,

$$W\!A(u)(x,a) = \sqrt{a} \int u(a(t-x))\overline{u(t)}dt,$$

in terms of wavelet frames, with the intent of solving the wideband radar ambiguity problem.

 We intend to complete our geometrical analysis of Shapiro-Rudin polynomials, and to extend the study to Golay pairs.



# Transition and the future

- We shall further develop and implement our theory of vector-valued ambiguity functions in terms of our notion of frame multiplication and the role of finite groups.
- Our previous MURI results on number theoretic CAZAC codes, such as Björck codes, serving as coefficients for phase-coded waveforms, will be analyzed in the vector-valued setting.
- We shall construct alternatives to the Golay waveform modality by means of our vector-valued theory.
- Gabor frames and pseudodifferential operators will be incorporated in our investigation of the narrow band radar ambiguity function
- We are using our frame potential characterization of FUNTFs in conjunction with  $L^1$ -sparse representation criteria in order to construction a new quantization scheme, called SRQP (Sparse Representation Quantization Procedure), which goes beyond  $\Sigma \Delta$ .







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