### **Graph Sparsification**

### Matthew Begué

Norbert Wiener Center Department of Mathematics University of Maryland, College Park



### Weighted Graphs

- We will only consider undirected, weighted graphs represented  $G = G(V, E, \omega)$ .
- *V* is the vertex set of size  $N < \infty$ .
- *E* is the edge set,  $E = \{(u, v) : u, v \in V \text{ and } u \sim v\}$ .
- Each edge is assigned a weight  $\omega_{u,v} > 0$ .
- For any x ∈ V, the degree of x, d<sub>x</sub>, is the sum of weights of edges originating from x.

$$d_{x} = \sum_{y \in V} \omega_{x,y}.$$



### **Graph Laplacian**

 For a finite graph, the Laplacian can be represented as a matrix. Let *D* denote the *N* × *N* degree matrix, *D* = diag(*d<sub>x</sub>*). Let *W* denote the *N* × *N* weighted adjacency matrix,

$$W(i,j) = \left\{ egin{array}{cc} \omega_{x_i,x_j}, & ext{if } x_i \sim x_j \ 0, & ext{otherwise.} \end{array} 
ight.$$

Then the unweighted graph Laplacian can be written as

$$L = D - W.$$

Equivalently,

$$L(i,j) = \begin{cases} d_{x_i} & \text{if } i = j \\ -\omega_{x_i,x_j} & \text{if } x_i \sim x_j \\ 0 & \text{otherwise.} \end{cases}$$



## Spectrum of the Laplacian

- *L* is a real symmetric matrix and therefore has nonnegative eigenvalues  $\{\lambda_k\}_{k=0}^{N-1}$  with associated orthonormal eigenvectors  $\{\varphi_k\}_{k=0}^{N-1}$ .
- If G is finite and connected, then we have

$$\mathbf{0} = \lambda_{\mathbf{0}} < \lambda_{\mathbf{1}} \leq \lambda_{\mathbf{2}} \leq \cdots \leq \lambda_{N-1}.$$

- The spectrum of the Laplacian, σ(L), is fixed but one's choice of eigenvectors {φ<sub>k</sub>}<sup>N-1</sup><sub>k=0</sub> can vary.
- Since *L* is Hermetian  $(L = L^*)$ , then we can choose the eigenbasis  $\{\varphi_k\}_{k=0}^{N-1}$  to be entirely real-valued.
- Easy to show that  $\varphi_0 \equiv 1/\sqrt{N}$ .



### A weighted graph and its Laplacian



(a) A random graph on 30 vertices



(b) Laplacian of the graph



### Problems arise with graphs with many edges





 A connected graph on N vertices can have as few as N – 1 edges,



• and can have as many as  $\frac{N(N-1)}{2}$  edges





### $\kappa$ -approximation

- Goal is to construct a subgraph, H = (V, Ĕ, ῶ), to be a κ-approximation of G.
- *H* is a  $\kappa$ -approximation of *G* if there exist  $B \ge A > 0$  with  $B/A \le \kappa$  such that for all  $x \in \mathbb{R}^N$ , we have

$$A \cdot x^{\top} L_G x \leq x^{\top} L_H x \leq B \cdot x^{\top} L_G x.$$

We write

$$A \cdot L_G \preceq L_G \preceq B \cdot L_G.$$

• This means for any i = 0, 1, ..., N - 1,

$$m{A} \leq rac{\lambda_i^{(H)}}{\lambda_i^{(G)}} \leq m{B}$$

Subgraph H has the same vertex set, V, as G. But we change to the edge set and the weights of those edges. In particular time context and the weights of those edges.

### $\kappa$ -approximation

- Goal is to construct a subgraph, H = (V, Ĕ, ῶ), to be a κ-approximation of G.
- *H* is a  $\kappa$ -approximation of *G* if there exist  $B \ge A > 0$  with  $B/A \le \kappa$  such that for all  $x \in \mathbb{R}^N$ , we have

$$A \cdot x^{\top} L_G x \leq x^{\top} L_H x \leq B \cdot x^{\top} L_G x.$$

We write

$$A \cdot L_G \preceq L_G \preceq B \cdot L_G.$$

• This means for any i = 0, 1, ..., N - 1,

$$m{A} \leq rac{\lambda_i^{(H)}}{\lambda_i^{(G)}} \leq m{B}$$

Subgraph H has the same vertex set, V, as G. But we change there center the edge set and the weights of those edges. In particular time changes application

### $\kappa$ -approximation

- Goal is to construct a subgraph, H = (V, Ĕ, ῶ), to be a κ-approximation of G.
- *H* is a  $\kappa$ -approximation of *G* if there exist  $B \ge A > 0$  with  $B/A \le \kappa$  such that for all  $x \in \mathbb{R}^N$ , we have

$$A \cdot x^{\top} L_G x \leq x^{\top} L_H x \leq B \cdot x^{\top} L_G x.$$

We write

$$A \cdot L_G \preceq L_G \preceq B \cdot L_G.$$

• This means for any i = 0, 1, ..., N - 1,

$$m{A} \leq rac{\lambda_i^{(H)}}{\lambda_i^{(G)}} \leq m{B}$$

Subgraph H has the same vertex set, V, as G. But we change the edge set and the weights of those edges. In particular E Context relations

## **Big Picture**



#### (a) A random graph on 30 vertices



#### (b) Laplacian of the graph



## Eigenvalues of *L*<sub>G</sub>





## Eigenvalues of *L*<sub>G</sub>





### Eigenvalues of $L_H$ will be contained in red region





#### Theorem

Let G be an undirected weighted graph on N vertices and let d > 1. There exists a weighted subgraph H with at most  $d \cdot N$  edges satisfying

$$\left(1-1/\sqrt{d}\right)^2 L_G \preceq L_H \preceq \left(1+1/\sqrt{d}\right)^2 L_G.$$

Hence, *H* is a  $\kappa = \left(\frac{1+1/\sqrt{d}}{1-1/\sqrt{d}}\right)^2$ -approximation of *G*.

 Joshua Batson, Daniel Spielman, Nikhil Srivastava, *Twice-Ramanujan Sparsifiers*, SIAM Review (2014) 56, no. 2, pp. 315-334.



### Method

 The Laplacian matrix, L<sub>G</sub>, can be written as a sum of rank-1 outer products

$$L_{\boldsymbol{G}} = \sum_{(\boldsymbol{u},\boldsymbol{v})\in\boldsymbol{E}} \omega_{\boldsymbol{u},\boldsymbol{v}} (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}}) (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}})^{\top}.$$

• The sparsified graph, *H*, will have Laplcian

$$L_H = \sum_{(u,v)\in E} \tilde{\omega}_{u,v} (\chi_u - \chi_v) (\chi_u - \chi_v)^{\top}$$

where at most  $d \cdot N$  of the  $\tilde{\omega} \neq 0$ .

 The weights ω̃<sub>u,v</sub> that are nonzero will be chosen so that the eigenvalues "play nice."



### Method

 The Laplacian matrix, L<sub>G</sub>, can be written as a sum of rank-1 outer products

$$L_{\boldsymbol{G}} = \sum_{(\boldsymbol{u},\boldsymbol{v})\in\boldsymbol{E}} \omega_{\boldsymbol{u},\boldsymbol{v}} (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}}) (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}})^{\top}.$$

• The sparsified graph, H, will have Laplcian

$$L_{H} = \sum_{(u,v)\in E} \tilde{\omega}_{u,v} (\chi_{u} - \chi_{v}) (\chi_{u} - \chi_{v})^{\top}$$

where at most  $d \cdot N$  of the  $\tilde{\omega} \neq 0$ .

 The weights ω̃<sub>u,v</sub> that are nonzero will be chosen so that the eigenvalues "play nice."



### Method

 The Laplacian matrix, L<sub>G</sub>, can be written as a sum of rank-1 outer products

$$L_{\boldsymbol{G}} = \sum_{(\boldsymbol{u},\boldsymbol{v})\in\boldsymbol{E}} \omega_{\boldsymbol{u},\boldsymbol{v}} (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}}) (\chi_{\boldsymbol{u}} - \chi_{\boldsymbol{v}})^{\top}.$$

• The sparsified graph, H, will have Laplcian

$$L_{H} = \sum_{(u,v)\in E} \tilde{\omega}_{u,v} (\chi_{u} - \chi_{v}) (\chi_{u} - \chi_{v})^{\top}$$

where at most  $d \cdot N$  of the  $\tilde{\omega} \neq 0$ .

 The weights ω̃<sub>u,v</sub> that are nonzero will be chosen so that the eigenvalues "play nice."



• Starting from  $A_0 = 0$ , we will construct  $A_n$  by adding a weighted outer product

$$\boldsymbol{A}_n = \boldsymbol{A}_{n-1} + \boldsymbol{s}_n \boldsymbol{v}_n \boldsymbol{v}_n^{\top}$$

where  $s_n > 0$  and  $v_n = \chi_u - \chi_v$  for some  $(u, v) \in E$ .

• The algorithm requires the selection of four positive constants,  $\epsilon_U, \epsilon_L, \delta_U, \delta_L$ .





$$A_0 = 0$$





# Step 1



$$A_1 = A_0 + s_1 \mathbf{v}_1 \mathbf{v}_1^{\mathsf{T}}$$







$$A_2 = A_1 + s_2 \mathbf{v}_2 \mathbf{v}_2^{\mathsf{T}}$$



Norbert Wiener Center for Harmonic Analysis and Applications

## Step 3



$$A_3 = A_2 + s_3 \mathbf{v}_3 \mathbf{v}_3^{\mathsf{T}}$$







$$L_H = A_{dN} + s_{dN} \mathbf{v}_{dN} \mathbf{v}_{dN}^{\top}$$





### Logistics

For all *d* · *N* iterations of the algorithm, there will always exist at least one admisible edge *v<sub>i</sub>* and scalar *s<sub>i</sub>* > 0 provided that

$$0 \leq 1/\delta_U + \epsilon_U \leq 1/\delta_L - \epsilon_L.$$

• Spielman gives constants

$$\delta_L = 1, \quad \delta_U = \frac{\sqrt{d}_1}{\sqrt{d} - 1}, \quad \epsilon_L = \frac{1}{\sqrt{d}}, \quad \epsilon_U = \frac{\sqrt{d} - 1}{d + \sqrt{d}},$$

that make the resulting graph H a  $\kappa$ -approximation of G for

$$\kappa = \left(\frac{1+1/\sqrt{d}}{1-1/\sqrt{d}}\right)^2$$

#### Theorem (B.)

This is the smallest value of  $\kappa$  that guarantees the Spielman algorithm will produce a  $\kappa$ -approximation of G with only d  $\cdot$  N edges.



### Logistics

For all *d* · *N* iterations of the algorithm, there will always exist at least one admisible edge *v<sub>i</sub>* and scalar *s<sub>i</sub>* > 0 provided that

$$0 \leq 1/\delta_U + \epsilon_U \leq 1/\delta_L - \epsilon_L.$$

Spielman gives constants

$$\delta_L = 1, \quad \delta_U = \frac{\sqrt{d}_1}{\sqrt{d} - 1}, \quad \epsilon_L = \frac{1}{\sqrt{d}}, \quad \epsilon_U = \frac{\sqrt{d} - 1}{d + \sqrt{d}},$$

that make the resulting graph H a  $\kappa$ -approximation of G for

$$\kappa = \left(\frac{1+1/\sqrt{d}}{1-1/\sqrt{d}}\right)^2$$

#### Theorem (B.)

This is the smallest value of  $\kappa$  that guarantees the Spielman algorithm will produce a  $\kappa$ -approximation of G with only d  $\cdot$  N edges.



### Logistics

For all *d* · *N* iterations of the algorithm, there will always exist at least one admisible edge *v<sub>i</sub>* and scalar *s<sub>i</sub>* > 0 provided that

$$0 \leq 1/\delta_U + \epsilon_U \leq 1/\delta_L - \epsilon_L.$$

Spielman gives constants

$$\delta_L = 1, \quad \delta_U = \frac{\sqrt{d}_1}{\sqrt{d} - 1}, \quad \epsilon_L = \frac{1}{\sqrt{d}}, \quad \epsilon_U = \frac{\sqrt{d} - 1}{d + \sqrt{d}},$$

that make the resulting graph H a  $\kappa$ -approximation of G for

$$\kappa = \left(\frac{1+1/\sqrt{d}}{1-1/\sqrt{d}}\right)^2$$

#### Theorem (B.)

This is the smallest value of  $\kappa$  that guarantees the Spielman algorithm will produce a  $\kappa$ -approximation of G with only d  $\cdot$  N edges.



Strengths

- This is a completely deterministic algorithm.
- There exists a method of sparsification via graph effective resistances which produces a κ-approximation of G with high probability.
- Daniel A. Spielman and Nikhil Srivastava, Graph sparsification by effective resistances, SIAM Journal on Computing, (2011)40 no.
   6, pp. 1913-1926.

Weaknesses

- Very computationally expensive. Each step requires inverting 3  $N \times N$  matrices.
- No information on the eigenvectors of L<sub>H</sub>
  - Wildly different in numerical experiments
  - Want to preserve eigenvectors to Fourier transform on sparsified graph.



Strengths

- This is a completely deterministic algorithm.
- There exists a method of sparsification via graph effective resistances which produces a κ-approximation of G with high probability.
- Daniel A. Spielman and Nikhil Srivastava, Graph sparsification by effective resistances, SIAM Journal on Computing, (2011)40 no.
   6, pp. 1913-1926.

Weaknesses

- Very computationally expensive. Each step requires inverting 3  $N \times N$  matrices.
- No information on the eigenvectors of L<sub>H</sub>
  - Wildly different in numerical experiments
  - Want to preserve eigenvectors to Fourier transform on sparsified graph.



## **Register for FFT today!**

#### **FEBRUARY FOURIER TALKS 2015**





