Distributed Noise Shaping of Signal Quantization

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Overview

Introduction

- Pulse Coding Modulation (PCM) Quantization
- Alternative Scheme: ΣΔ and Noise Shaping
- 2 Adaptation to Finite Dimensional Space
 - Quantization on Frame Setting
 - Modification on Dual Frame
- Oistributed Noise Shaping: Beta Dual
 - Main Result
 - Setting of Distributed Noise Shaping
 - Beta Dual for Unitarily Generated Frames



Reference

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A/D Conversion for Signals

Theorem (Classical Sampling Theorem)

Given $f \in PW_{[-1/2,1/2]}$, i.e., $f, \hat{f} \in L^2(\mathbb{R})$, and $supp(\hat{f}) \subset [-1/2, 1/2]$. Then for any g satisfying

- $\hat{g}(\omega) = 1$ on [-1/2, 1/2]
- $\hat{g}(\omega) = 0$ for $|\omega| \ge 1/2 + \epsilon$,

and for any $T \in (0, 1 - 2\epsilon)$, $t \in \mathbb{R}$,

$$f(t) = T \sum_{n \in \mathbb{Z}} f(nT)g(t - nT)$$
(1)

where the convergence is both uniform on compact sets and in L^2 .

Remark

f has a continuous representative, so it makes sense to evaluate *f* at points.

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Figure: Black: Signal f, Red: Reconstruction Kernel g

- In particular, it is only necessary to store {*f*(*nT*)}_{*n*∈ℤ} to reconstruct *f*.
- Computers cannot store real numbers, so instead Notert Wiener Center $\{q_n\}_{n\in\mathbb{Z}}\subset \mathscr{A}$ is considered where \mathscr{A} is a finite subset of \mathbb{R} .

Pulse Coding Modulation (PCM) Quantization

Naive Approach: Pulse Coding Modulation (PCM)

Given a finite alphabet $\mathscr{A} \subset \mathbb{R}$, define $Q : \mathbb{R} \to \mathscr{A}$ by

$$Q(x) = \underset{q \in \mathscr{A}}{\arg\min} |x - q|$$
 (2)

For a bandlimited function $f \in PW_{[-1/2,1/2]}$, its reconstructed function via PCM will be

$$\tilde{f}(t) = T \sum_{n \in \mathbb{Z}} Q(f(nT))g(t - nT)$$
(3)

Remark

In practice, mid-rise uniform quantizer is often used. That is,

$$\mathscr{A} = \{(k+1/2)\delta: k = -N, \dots, N-1\}$$

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Pulse Coding Modulation (PCM) Quantization

Reconstruction Error Estimate of PCM

For the mid-rise uniform quantizer, the reconstruction error is

$$|f(t) - \tilde{f}(t)| = T |\sum_{n \in \mathbb{Z}} \left(f(nT) - Q(f(nT)) \right) g(t - nT)|$$

$$\leq \delta \cdot T \sum_{n \in \mathbb{Z}} |g(t - nT)|$$

$$= C_{g,T} \cdot \delta$$
(5)

Remark

 $C_{g,T} \to \|g\|_1$ as $T \to 0^+$, so oversampling doesn't improve the reconstruction significantly.

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Pulse Coding Modulation (PCM) Quantization

Caveat of PCM: Imperfect Quantizers

Consider the following imperfect base quantizer

$$Q_1(x) = \begin{cases} 0 & \text{if } x \leq \frac{1}{2} - \epsilon \\ 1 & \text{if } x \geq \frac{1}{2} + \epsilon \\ 0 \text{ or } 1 & \text{if } x \in (\frac{1}{2} - \epsilon, \frac{1}{2} + \epsilon) \end{cases}$$
(6)

For $x \in (0, 1)$, Let

$$Q^{k}(x) = \sum_{n=1}^{k} \frac{Q_{n}(x)}{2^{n}}$$
(7)

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where $Q_n(x) = Q_1(2^{n-1}(x - \sum_{s=1}^{n-1} \frac{Q_s(x)}{2^s})).$

Pulse Coding Modulation (PCM) Quantization



Figure: Illustration of Imperfect Quantization



Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

Alternative Option: $\Sigma\Delta$ Quantization

Introduce auxiliary variable $\{u_n\}_{n \in \mathbb{Z}}$ and the recursive equation

$$u_{n+1} = u_n + f(nT) - q_n$$
 (8)

where $q_n = Q(u_n + f(nT))$ for each *n*.

Proposition (Uniform Boundedness of $\{u_n\}$)

With the choice of mid-rise uniform quantizer $\mathscr{A} = \{(k + 1/2)\delta : k = -N, ..., N - 1\}, ||u||_{\infty} < \delta$ if $\sup |f(nT)| \le (N - 1)\delta.$ We call such scheme a stable $\Sigma\Delta$ quantization scheme.

Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

Reconstruction Error for $\Sigma\Delta$ Quantization

Consider the reconstructed signal

$$\tilde{f}(t) = T \sum_{n \in \mathbb{Z}} q_n g(t - nT)$$
(9)

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Then the reconstruction error is

$$\begin{split} |f(t) - \tilde{f}(t)| &= |T \sum_{n \in \mathbb{Z}} (f(nT) - q_n)g(t - nT)| \\ &= |T \sum_{n \in \mathbb{Z}} (u_{n+1} - u_n)g(t - nT)| \\ &= |T \sum_{n \in \mathbb{Z}} u_n(g(t - nT) - g(t - (n - 1)T))| \qquad (10) \\ &= |T \sum_{n \in \mathbb{Z}} u_n \int_{(n-1)T}^{nT} g'(t - u) du| \\ &\leq T ||u||_{\infty} ||g'||_1 \to 0 \quad \text{as } T \to 0 \end{split}$$
Note that g is independent of T .

Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

Robustness of $\Sigma \Delta$ Against Imperfect Quantizer

• For $\Sigma\Delta$ quantization, the scheme is

$$u_{n+1} = u_n + f(nT) - q_n$$
 (11)

- Imperfect quantizer Q gives a larger sup-norm for {u_n}. In particular, it now changes to ||u||_∞ ≤ δ + ε.
- However, the scheme can still be stable, and the reconstruction error is still

$$\|f - \tilde{f}\|_{\infty} \le T \|u\|_{\infty} \|g'\|_1$$
 (12)



Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

r-th Order $\Sigma\Delta$ Quantization

It is now a natural step to consider the following scheme:

$$y - q = \Delta^r u \tag{13}$$

Existence of a stable scheme of such kind is proven in [6, Daubechies & DeVore (2003)].

Proposition (Error decay for high order $\Sigma \Delta$)

Let f and \tilde{f} as before, except that $\{q_n\}$ now comes from (13). Suppose the kernel $g \in C^r$, then

$$\|f - \tilde{f}\|_{\infty} \le T^r \|u\|_{\infty} \|g^{(r)}\|_{\infty}$$
(14)

Again, both $||u||_{\infty}$ and $||g^{(r)}||_{\infty}$ are independent of sampling period T.

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Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

Noise Shaping Feature of $\Sigma \Delta$ Quantization



Figure: Classical noise shaping via $\Sigma\Delta$ modulation[5, Chou, Gunturk, Krahmer, Saab, Yilmaz (2015)]

Black Fourier spectra of a bandlimited signal Red Quantization error signals using PCM Pink Error signal for 1st order $\Sigma\Delta$ quantization Blue Error signal for 2nd order $\Sigma\Delta$ quantization



Alternative Scheme: $\Sigma\Delta$ and Noise Shaping

Generalization: Noise Shaping Quantization

Instead of difference operator Δ , consider the following scheme:

$$y - q = h * u \tag{15}$$

where

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$$h = \{h_n\}_n \in \mathbb{N}$$
 has $h_0 = 1$, and

$$(h * u)_n = \sum_{m=0}^{\infty} h_m u_{n-m}$$

[8, Gunturk, 2003] constructed a family of *h* to achieve exponential decay, with sub-optimal exponent.



- Pulse Coding Modulation (PCM) Quantization
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Adaptation to Finite Dimensional Space

- Quantization on Frame Setting
- Modification on Dual Frame

3 Distributed Noise Shaping: Beta Dual

- Main Result
- Setting of Distributed Noise Shaping
- Beta Dual for Unitarily Generated Frames

Reference



Quantization on Frame Setting

Finite Frame and Quantization

For a given space \mathbb{F}^k where $\mathbb{F} = \mathbb{R}$ or \mathbb{C} , suppose $\{e_n\}_{n=1}^m \subset \mathbb{F}^k$ is a spanning set and let the rows of $E \in \mathbb{F}^{m \times k}$ be $\{e_n^*\}$, the conjugate transpose of $\{e_n\}$. Then for any dual $F \in \mathbb{F}^{k \times m}$, we have

$$FE = I_k$$
 (16)

In particular, if $F = (f_1 \mid \cdots \mid f_m)$, then for any $x \in \mathbb{F}^k$,

$$x = \sum_{n=1}^{m} \langle x, e_n \rangle f_n$$
 (17)

where $f_n \in \mathbb{F}^k$. Then the quantized version \tilde{x} shall be

ñ

$$= \sum_{n=1}^{m} q_n f_n$$

Quantization on Frame Setting

First Order $\Sigma \Delta$ Quantization for Finite Frames

Consider the following scheme:

$$y - q = \Delta u \tag{19}$$

Then the reconstruction error $\|x - \tilde{x}\|_2$ is

$$\|x - \tilde{x}\|_{2} = \|\sum_{n=1}^{m} (\langle x, e_{n} \rangle - q_{n})f_{n}\|_{2}$$

$$= \|\sum_{n=1}^{m} ((u_{n} - u_{n-1})f_{n})\|_{2}$$

$$= \|\sum_{n=1}^{m} u_{n}(f_{n} - f_{n+1}) + u_{m}f_{m}\|_{2}$$

$$\leq \|u\|_{\infty} (\sum_{n=1}^{m} \|f_{n} - f_{n+1}\|_{2} + \|f_{m}\|_{2})$$
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$$\|u\|_{\infty} (\sum_{n=1}^{m} \|f_{n} - f_{n+1}\|_{2} + \|f_{m}\|_{2})$$

Quantization on Frame Setting

Frame Analogy of $\Sigma \Delta$ Quantization[1]

Definition (Frame Variation)

Let $E = \{e_n\}_{n=1}^m$ be a finite frame for \mathbb{R}^k , and p a permutation of $\{1, 2, ..., N\}$. The variation of the frame E with respect to p is

$$\sigma(E,p) := \sum_{n=1}^{m-1} \|e_{p(n)} - e_{p(n+1)}\|_2$$
(21)

Theorem ([1], Benedetto, Powell, Yilmaz, 2006)

Suppose $E = \{e_n\}_{n=1}^m$ is a zero-sum FUNTF with frame bound m/k. Then the reconstruction error $||x - \tilde{x}||_2$ satisfies

$$\|x - \tilde{x}\|_{2} \leq \begin{cases} \frac{\delta k}{2m} \sigma(E, p) & \text{if } m \text{ is even} \\ \frac{\delta k}{2m} (\sigma(E, p) + 1) & \text{if } m \text{ is odd} \end{cases}$$
(22)

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Modification on Dual Frame

Definition

Let \mathscr{B} be the unit ball centered around origin of \mathbb{F}^m . A map $Q : \mathscr{B} \to \mathscr{A}^m$ is a stable noise shaping scheme if $\exists H$: lower triangular, $\{u_n\}$ uniformly bounded by δ such that

$$y - q = Hu \tag{23}$$

where q = Q(y) and we use $\tilde{x} = Fq$ as the reconstruction vector for *x*.

- Stability: [4, Chou, Gunturk, 2016] gives a sufficient condition for such scheme to work
- Recursiveness: Requires *H* to be lower triangular



Modification on Dual Frame

Reconstruction Frame/ Kernel F

Many choices. Depends on *H* in quantization scheme (||x - Fq|| = ||F(y - q)|| = ||FHu||)

- Canonical dual: E[†]
- V-dual: $(VE)^{\dagger}V$ such that VE is still a frame.
 - Sobolev dual [2]: (Δ⁻¹E)[†]Δ⁻¹ achieves minimum 2-norm for FΔ.
 - 2 Alternative dual: $(H^{-1}E)^{\dagger}H^{-1}$
 - **③** Beta dual: $(V_{\beta}E)^{\dagger}V_{\beta}$, V_{β} to be specified later.

How does the choice of V affect our reconstruction?



Modification on Dual Frame

De-Noising Aspect of Dual Frame



Figure: Error Cutoff Procedures for Different Quantization Schemes

For $M \in \mathbb{F}^{\ell \times k}$ injective, $ker(M^{\dagger}) = (M(\mathbb{F}^k))^{\perp}$.

Modification on Dual Frame



Figure: Different alternative duals for the 15th roots-of-unity frame the roots \mathbb{R}^2 [5]

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Main Result

Theorem (Chou, Gunturk)

Given a unitarily generated frame Φ with generator Ω , a $k \times k$ Hermitian matrix with $\{v_s\}_{s=1}^k$ being a basis of orthonormal eigenvectors and $\phi_0 \in \mathbb{F}^k$. Suppose the eigenvalues are all distinct modulo I where $l \ge k$, then we have

$$\|x - F_V q\|_2 < 7e\left(\frac{m}{l} + 1\right)c(\phi_0) \cdot \begin{cases} \sqrt{2}\lfloor \sqrt{L} \rfloor^{-m/l} & \text{if } \mathbb{F} = \mathbb{C} \\ L^{-m/l} & \text{if } \mathbb{F} = \mathbb{R} \end{cases}$$
(24)

where

$$c(\phi_0) := \left(\min_{1 \le s \le k} | < \phi_0, v_s > |\right)^{-1}$$
(25)

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Setting of Distributed Noise Shaping

Setup of Distributed Noise Shaping (DNS)

Definition (V-dual)

Let $E \in \mathbb{R}^{m \times k}$ be a frame, m > k. $F_V \in \mathbb{R}^{k \times m}$ is a V-dual of E if

$$F_V = (VE)^{\dagger}V \tag{26}$$

where $V \in \mathbb{R}^{p \times m}$ such that *VE* is still a frame.

Recall that a stable noise shaping scheme has

$$y - q = Hu \tag{27}$$



Setting of Distributed Noise Shaping

Setup of DNS (Cont'd)

In the setting of DNS, $V \in \mathbb{R}^{p \times m}$ and $H \in \mathbb{R}^{m \times m}$ are block matrices

$$V = \begin{pmatrix} V_1 & & \\ & V_2 & \\ & & V_3 & \\ & & \ddots & \\ & & & V_i \end{pmatrix}, \quad H = \begin{pmatrix} H_1 & & \\ & H_2 & & \\ & & H_3 & \\ & & & \ddots & \\ & & & H_i \end{pmatrix}$$
(28)
where $V_i \in \mathbb{R}^{p_i \times m_i}$, $H_i \in \mathbb{R}^{m_i \times m_i}$ with $\sum p_i = p$, $\sum m_i = m$.

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Setting of Distributed Noise Shaping

 β -Dual

Definition (β -dual)

A β -dual $F_V = (VE)^{\dagger}V$ has $V = V_{\beta,m}$, where $\beta = [\beta_1, \dots, \beta_l]^t$ and $\boldsymbol{m} = [m_1, \dots, m_l]^t$, is a *l*-by-*m* block matrix such that $V_i = [\beta_i^{-1}, \beta_j^{-2}, \dots, \beta_i^{-m_i}] \in \mathbb{R}^{1 \times m_i}$, i.e. l = p.

- {β_i} satisfies β_i > 1 for every 1 ≤ i ≤ l, whose choice is limited by a technical lemma.
- Under this setting, each H_i is chosen to be a $m_i \times m_i$ matrix with unit diagonal entries and $-\beta_i$ sub-diagonal entries.



Signal Quantization

Distributed Noise Shaping: Beta Dual

Setting of Distributed Noise Shaping

β -Dual (Cont'd)

$$V_{i}H_{i} = \begin{bmatrix} \beta_{i}^{-1}\beta_{i}^{-2}\cdots\beta_{i}^{-m_{i}}\end{bmatrix} \begin{pmatrix} 1 & & & \\ -\beta_{i} & 1 & & \\ 0 & -\beta_{i} & 1 & \\ 0 & 0 & \ddots & \ddots & \\ & & & -\beta_{i} & 1 \end{pmatrix}$$
(29)
$$= \begin{pmatrix} 0 & 0 & \cdots & 0 & \beta_{i}^{-m_{i}} \end{pmatrix}$$

where $\beta_i > 1$, so it effectively reduced the size of error.



Setting of Distributed Noise Shaping

Reconstruction Error Estimate for β -Dual

Lemma (Chou, Gunturk, 2016)

Given a β -dual V, suppose VE is a frame, then the reconstruction error is

$$\begin{aligned} \|x - F_{V}q\|_{2} &= \|F_{V}Hu\|_{2} \leq \|F_{V}H\|_{\infty \to 2} \|u\|_{\infty} \\ &\leq \|u\|_{\infty} \frac{1}{\sigma_{\min}(VE)} \|VH\|_{\infty \to 2} \\ &\leq \frac{\sqrt{l}}{\sigma_{\min}(VE)} \delta\beta^{-\lfloor m/l \rfloor} \\ &< \frac{\|E\|_{2 \to \infty} e(1 + \lfloor m/l \rfloor)\sqrt{l}}{\sigma_{\min}(VE)} L^{-(\lfloor m/l \rfloor + 1)} \end{aligned}$$
(30)

Beta Dual for Unitarily Generated Frames

Proof of Theorem[3]

- Assume that $m/I \in \mathbb{N}$ for simplicity.
- Assumption: Eigenvalues $\{\lambda_s\}$ are distinct modulo *I*.
- σ_{min}(VE) can be controlled uniformly for all *m* in such setting. ||E||_{2→∞} is easily seen to be uniformly bounded.

Given a $k \times k$ Hermitian matrix Ω and $\phi_0 \in \mathbb{F}^k$, consider

$$U_t := e^{2\pi i \Omega t}, \quad \phi_n = U_{\frac{n}{m}} \phi_0, \quad n = 0, \dots, m-1$$
(31)

Set E to be the collection of such elements, that is,

$$E = \begin{pmatrix} \phi_0^* \\ \vdots \\ \phi_{m-1}^* \end{pmatrix} = \begin{pmatrix} E_1 \\ \vdots \\ E_l \end{pmatrix}$$
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Signal Quantization

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Proof (Cont'd)

Then,

$$VE = \begin{pmatrix} V_1 E_1 \\ \vdots \\ V_l E_l \end{pmatrix}$$
(33)

where

$$(V_j E_j)^* = \sum_{n=1}^{m/l} \beta^{-n} \phi_{(j-1)m/l+n} \in \mathbb{F}^k$$
 (34)



Beta Dual for Unitarily Generated Frames

Now, let $\{v_s\}$ be an ONB of eigenvectors with respect to Ω with eigenvalue $\{\lambda_s\}$. Then

$$< (V_{j}E_{j})^{*}, V_{s} > = \sum_{n=1}^{m/l} \beta^{-n} < U_{\frac{(j-1)m/l+n}{m}} \phi_{0}, V_{s} >$$

$$= \sum_{n=1}^{m/l} \beta^{-n} < \phi_{0}, U_{\frac{-(j-1)m/l-n}{m}} V_{s} >$$

$$= \sum_{n=1}^{m/l} \beta^{-n} e^{-2\pi \imath \frac{(j-1)m/l+n}{m} \lambda_{s}} < \phi_{0}, V_{s} >$$

$$= e^{-2\pi \imath \frac{(j-1)}{l} \lambda_{s}} W_{s} < \phi_{0}, V_{s} >$$
(35)

where

$$W_{s} = \sum_{n=1}^{m/l} \left(\beta^{-1} e^{2\pi i \lambda_{s}/m}\right)^{n}$$



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Signal Quantization

Distributed Noise Shaping: Beta Dual

Beta Dual for Unitarily Generated Frames

Remark

$$|w_{s}| = |\sum_{n=1}^{m/l} \left(\beta^{-1} e^{2\pi i \lambda_{s}/m}\right)^{n}| = \left|\frac{1 - \beta^{-m/l} e^{2\pi i \lambda_{s}/l}}{1 - \beta^{-1} e^{2\pi i \lambda_{s}/m}}\right| \ge \frac{1 - \beta^{-1}}{1 + \beta^{-1}}$$
(37)



Signal Quantization

Distributed Noise Shaping: Beta Dual

Beta Dual for Unitarily Generated Frames

Then, for any $x \in \mathbb{F}^k$,

$$\begin{split} VEx \|_{2}^{2} &= \sum_{j=1}^{l} |V_{j}E_{j}x|^{2} \\ &= \sum_{j=1}^{l} |\sum_{s=1}^{k} < (V_{j}E_{j})^{*}, v_{s} > < x, v_{s} > |^{2} \\ &= \sum_{s=1}^{k} \sum_{t=1}^{k} < x, v_{s} > < v_{t}, x > < \phi_{0}, v_{s} > < v_{s}, \phi_{0} > w_{s}\bar{w}_{t} \sum_{j=1}^{l} e^{2\pi i (j-1)(\lambda_{t}-\lambda_{s})/l} \\ &= l \sum_{s=1}^{k} |< x, v_{s} > |^{2} |< \phi_{0}, v_{s} > |^{2} |w_{s}|^{2} \\ &\geq l \left(\frac{1-\beta^{-1}}{1+\beta^{-1}}\right)^{2} \min_{1 \le s \le k} |< \phi_{0}, v_{s} > |^{2} ||x||_{2}^{2} \end{split}$$

if $\lambda_s - \lambda_t$ are integers and nonzero modulo *I*.

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